Nonlinearity stability of active suspension model

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Phase mixing 00 Active suspension mode

Phase mixing for $v \in \mathbb{S}^{d}$.

Macroscopic behaviour from microscopic laws

Statistical physics: many particle systems

- Microscopic laws: reversible
- Macroscopic laws: irreversible (thermodynamic)
- **Kinetic theory**: density over phase space (x, v)
 - with collisions by Boltzmann and Maxwell
 ⇒ H theorem
 - collisionless by Jeans (gravitational) and Vlasov (plasmas)
 ⇒ reversible
 - \Rightarrow Landau (1946) damping

Phase mixing



Phase mixing for free transport

Density f(t, x, v) evolves over phase space $(x, v) \in \mathbb{T} \times \mathbb{R}$ as

$$\partial_t f + v \partial_x f = 0.$$



Fourier transform $x \rightarrow k$:

 $\partial_t f_k + ikvf_k = 0 \quad \Rightarrow \quad f_k(t, v) = e^{-ikvt} f_k^{in}(v)$

Spatial density

$$\rho_k(t) = \int_{v \in \mathbb{R}} f_k(t, v) \, \mathrm{d}v = \int_{v \in \mathbb{R}} \mathrm{e}^{-\mathrm{i}kvt} f_k^{\mathrm{in}}(v) \, \mathrm{d}v$$

decays if f^{in} has regularity.

Phase mixing ○● Active suspension model

Phase mixing for $v \in \mathbb{S}^{d}$

Model [Saintillan, Shelley '08]

Active particles (bacteria) in a Stokes fluid described by

- position $x \in \mathbb{T}^3$,
- orientation $v \in \mathbb{S}^2$.

Each particle moves forward \Rightarrow Induced velocity field *u*.

Density f(t, x, v) evolves as

$$\begin{cases} \partial_t f + (v+u) \cdot \nabla_x f + \nabla_v \cdot \left(\mathbb{P}_{v^{\perp}} \left[(\gamma E(u) + W(u)) v \right] f \right) = \nu \Delta_v f, \\ -\Delta_x u + \nabla_x q = \alpha \nabla_x \cdot \int_{\mathbb{S}^2} f(t, x, v) v \otimes v \, \mathrm{d} v, \\ \nabla_x \cdot u = 0. \end{cases}$$

$$\begin{split} E(u) &= \frac{1}{2} \left[\nabla_x u + (\nabla_x u)^T \right] \quad \text{and} \quad W(u) = \frac{1}{2} \left[\nabla_x u - (\nabla_x u)^T \right] \\ \text{Pusher:} \quad \alpha < 0 \qquad \qquad \text{Puller:} \quad \alpha > 0 \end{split}$$

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Phase mixing for $v \in S'$ 0000000

Popular model. For pushers, simulations show a phase transition more or less observed in experiments:

- For $\gamma |\alpha|$ small enough, the incoherent state $f(v) = \frac{1}{4\pi}$ is stable.
- For $\gamma |\alpha|$ big enough, emergence of a new collective behaviour. Changes the rheology of the suspension.
- Goal: Recover observations analytically

First step: Understand the linearised behaviour

In the incoherent regime, we exhibit a mixing phenomenon, both at $\nu = 0$ and $\nu \gg 1 > 0$ (much harder). The fact that $\nu \in \mathbb{S}^2$ changes deeply the behaviour with respect to usual settings.

Phase mixing 00 Linearise around the incoherent state:

- Fourier modes $x \rightarrow k$ decouple
- Can rescale k to |k| = 1 in adimensional form

Fixed mode $k \in \mathbb{S}^2$, perturbation $f = f(t, v), v \in \mathbb{S}^2$, evolves as

$$\begin{cases} \partial_t f + \mathrm{i} v \cdot kf - \frac{3\Gamma}{4\pi} v \otimes v : E(u) = \nu \Delta_v f, \\ u = \mathbb{P}_{k^{\perp}} \mathrm{i} k \Sigma, \\ \Sigma := \epsilon \int_{S^2} f(t, v) v \otimes v \, \mathrm{d} v \end{cases}$$

where $\epsilon = \pm 1$ (pullers $\epsilon = 1$, pushers $\epsilon = -1$) and strength number Γ .

Theorem ($\nu = 0$: mixing)

If $\epsilon=1$ (pullers), for any Γ , as $t \to \infty$

$$|u(t)| = O(t^{-2}), \qquad \|\psi\|_{H^{-1-}} = O(t^{-1}).$$

If $\epsilon = -1$ (pushers), there exists Γ_c such that

- For $\Gamma < \Gamma_c$, the same stability result holds.
- For $\Gamma > \Gamma_c$, there exist unstable eigenmodes.

Theorem ($\nu > 0$: mixing followed by enhanced dissipation)

If $\epsilon = 1$ or $\epsilon = -1$ and $\Gamma < \Gamma_c$, then for ν small enough

$$|u(t)|+rac{1}{t}\|\psi\|_{H^{-1-}}\lesssim\min\left(rac{|\ln t|^M}{t^2},\mathrm{e}^{-\eta
urac{1}{2}t}
ight)$$

Phase mixing 00 **Remark:** Decay due to mixing is at fixed polynomial rate, even for analytic f_{in} . Strong difference with usual results due to $v \in \mathbb{S}^2$ instead of $v \in \mathbb{R}^3$.

Remark: Contemporary paper by [Albritton-Ohm] on the same model.

• $\nu = 0$: Under stability condition from dispersion relation, L^2 decay as

$$\int_{t=0}^{\infty} |u(t)|^2 (1+t)^{3-\epsilon} \,\mathrm{d}t < \infty$$

• $\nu > 0$: No analogue of our theorem. Only result of enhanced dissipation under stringent assumption $\Gamma \ll \nu^{1/2}$.

Decay by phase mixing and diffusion

Key step

Understand phase mixing and diffusion (Fourier mode $x \rightarrow k$):

$$(\partial_t - L_1)f_k = (\partial_t + ik \cdot v - \nu \Delta_v)f_k = 0, \quad f_k = f_k(t, v), t \in \mathbb{R}^+, v \in \mathbb{S}^2$$

where we can rescale $k \in \mathbb{S}^2$.

Challenge: Phase mixing is degenerate at poles $\pm k$

Similar to mixing through Poiseuille flow:



Common theme for phase mixing of trapped particles.

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Phase mixing for $v \in \mathbb{S}^{d-1}$

$$(\partial_t - L_1)f = (\partial_t + \mathrm{i}k \cdot v - \nu \Delta_v)f = 0, \qquad f = f(t, v), t \in \mathbb{R}^+, k, v \in \mathbb{S}^2.$$

Proposition (inviscid decay)

For $\nu = 0$ and $\delta > 0$ and weight $F : \mathbb{S}^2 \to \mathbb{R}$

$$\begin{split} \left| \int_{\mathbb{S}^2} f(t, v) F(v) \, \mathrm{d}v \right| \lesssim \frac{1}{(1+t)} \|F\|_{H^{1+\delta}} \|f\|_{H^{1+\delta}}, \\ \left| \int_{\mathbb{S}^2} f(t, v) F(v) \nabla(k \cdot v) \, \mathrm{d}v \right| \lesssim \frac{1}{(1+t)^2} \|F\|_{H^{2+\delta}} \|f\|_{H^{2+\delta}}. \end{split}$$

Idea: Solve explicitly and use stationary phase.

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Phase mixing for $v \in \mathbb{S}^{d-1}$

Decay by phase mixing and diffusion

$$(\partial_t - L_1)f = (\partial_t + \mathrm{i}k \cdot v - \nu\Delta_v)f = 0, \quad f = f(t, v), t \in \mathbb{R}^+, k, v \in \mathbb{S}^2.$$

Small degenerate diffusion $(0 < \nu \ll 1)$?

(collisions in kinetic theory (Boltzmann/Landau operator), viscosity in fluids) **Hypocoercivity:** Decay by combination of

transport and degenerate dissipation.

Decay rate for $u \ll 1$: Faster as simple diffusion as

- transport pushes perturbations to high Fourier frequencies,
- dissipation is faster for high Fourier frequencies.

Proposition (enhanced dissipation)

There exists $\nu_0, \lambda > 0$ such that for $0 < \nu < \nu_0$

$$\|f(t,\cdot)\|_{L^2(\mathbb{S}^2)} \lesssim \mathrm{e}^{-\lambda\nu^{\frac{1}{2}}t} \|f^{\mathrm{in}}\|_{L^2(\mathbb{S}^2)}.$$

Idea: Use functional with commutator brackets.

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Phase mixing for $v \in \mathbb{S}^{d-1}$ 000000

Decay of induced velocity field u (macroscopic quantity)





Proposition (Persistence of phase mixing)

For 0 $< \nu \ll 1$ and t $\lesssim \nu^{-1/2} |\log \nu|$

$$\begin{split} \left| \int_{\mathbb{S}^2} f(t,v) \, F(v) \, \mathrm{d}v \right| \lesssim_{\log} \frac{1}{(1+t)} \|F\|_{H^{1+\delta}} \|f\|_{H^{1+\delta}}, \\ \left| \int_{\mathbb{S}^2} f(t,v) \, F(v) \, \nabla(k \cdot v) \, \mathrm{d}v \right| \lesssim_{\log} \frac{1}{(1+t)^2} \|F\|_{H^{2+\delta}} \|f\|_{H^{2+\delta}}. \end{split}$$

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Proof ideas

Consider the hypocoercive functional (a, b, c suitable constants):

$$E(t) = \frac{1}{2} \Big[\|f\|^2 + a\nu t \|\nabla f\|^2 + 2b\nu t^2 \Re \langle i\nabla (k \cdot v)f, \nabla f \rangle + c\nu t^3 \|\nabla (k \cdot v)f\|^2 \Big]$$

In considered time-frame:

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t} E(t) + \frac{\nu}{2} \|\nabla f\|^2 + \frac{a\nu^2 t}{2} \|\nabla \nabla f\|^2 + \frac{b\nu t^2}{2} \|\nabla (k \cdot v)f\|^2 \\ + \frac{c\nu^2 t^3}{2} \|\nabla (\nabla (k \cdot v)f)\|^2 \lesssim \mathsf{OK} \end{aligned}$$

Enhanced dissipation follows from interpolation

Lemma (interpolation)

For $\sigma \in (0,1]$

$$\sigma^{1/2} \|g\|^2 \leq \frac{\sigma}{2} \|\nabla g\|^2 + 2 \|\nabla (k \cdot v)g\|^2.$$

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Phase mixing for $v \in \mathbb{S}^{d-1}$ 0000000 Volterra equation

Nonlinear stability

Proof ideas for mixing

Use vector-field method:

Inviscid case ($\nu = 0$)

Consider *Jf* for $J = \nabla + it\nabla(k \cdot v)$:

$$(\partial_t + ik \cdot v)f = 0 \quad \Rightarrow \quad (\partial_t + ik \cdot v)Jf = 0$$

Control on $Jf \Rightarrow$ time decay

With viscosity:

$$(\partial_t - L_1)Jf + \nu Jf = 2i\nu t (\nabla (k \cdot v)f + (k \cdot v)\nabla f).$$

Expected bounds

$$\|f(t)\|_{L^2} \lesssim 1, \quad \|
abla f(t)\|_{L^2} \lesssim t$$

would yield

$$\|Jf(t)\|_{L^2}\leq C\Big(1+
u\int_0^t s(1+s)\,\mathrm{d}s\Big),\qquad orall t\leq
u^{-1/2}.$$

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Phase mixing for $v \in \mathbb{S}^{d-1}$

Idea: Use viscosity adapted vector fields

$$J_{\nu}f = \alpha(t)\nabla f + \mathrm{i}\beta(t)\nabla(k\cdot\nu)f$$

where $\beta'=\alpha$ and $\alpha'=-2i\nu\beta$ so that

$$lpha(t) = \cosh(\sqrt{-2\mathrm{i}
u}\,t) ext{ and } eta(t) = rac{1}{\sqrt{-2\mathrm{i}
u}} \sinh(\sqrt{-2\mathrm{i}
u}\,t).$$

New error

$$\left(\partial_t + \mathrm{i}(k \cdot \mathbf{v}) - \nu \Delta\right) J_{\nu}f + \nu J_{\nu}f = 2\mathrm{i}\beta\nu\nabla([k \cdot \mathbf{v} - 1]f)$$

localised **away** from pole v = k.

Phase mixing 00

Volterra equation

To conclude for the linearised evolution, use Duhamel's formula to get Volterra equation for u:

$$u(t) + \int_0^t K_\nu(t-s)u(s)\,\mathrm{d}s = g(t)$$

where

$$\begin{split} \mathcal{K}_{\nu}(t) w \cdot \bar{w} &= \frac{3\epsilon\Gamma}{4\pi} \int_{\mathbb{S}^2} \mathrm{e}^{L_1 t} (\mathbb{P}_{k^{\perp}} k \cdot w) (\mathbb{P}_{k^{\perp}} k \cdot \bar{w}) \,\mathrm{d}v \\ g(t) &= \mathrm{i}\epsilon \int_{S^2} \mathrm{e}^{L_1 t} f_{\mathrm{in}}(k, v) \mathbb{P}_{k^{\perp}} k \,\mathrm{d}v \end{split}$$

Key point: Obtain $O(t^{-2})$ decay for u! **Steps:**

$$lacksymbol{0}$$
 Prove $O(t^{-2})$ decay for $K_
u$ and g

2 Identify condition on Γ to transfer decay to u

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Transfer of decay in Volterra equation

Classical theory for Volterra equation $u(t) + \int_0^t K(t-s)u(s) ds = g(t)$:

Theorem (Paley-Wiener, see [Gripenberg et al])

If $g \in L^p(\mathbb{R}^+)$ and $K \in L^1(\mathbb{R}^+)$, and if its Laplace transform satisfies

$$\det(I + \mathcal{L}K(z)) \neq 0, \qquad \forall \Re z \ge 0 \tag{Lap}$$

then the Volterra equation has a unique solution in $u \in L^p(\mathbb{R}^+)$.

Not quantitative and for exponential decay. We show

Theorem (Quantitative version)

If $g, K \in O(t^{-\alpha})$, $\alpha > 1$ and (Lap), then $u \in O(t^{-\alpha})$.

Remark: Already known? Various quantitative statements in literature.

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Solution of the Volterra equation

Our proof is to write

$$egin{aligned} &(ilde{u}, ilde{g}) := (1+\epsilon t)^lpha(u,g), \ &k(t,s) := \left(rac{1+\epsilon t}{1+\epsilon s}
ight)^lpha \mathcal{K}(t-s) \mathbf{1}_{s< t}, \ & ilde{u}(t) + \int_{s=0}^t k(t,s) ilde{u}(s) \,\mathrm{d}s = ilde{g}(t). \end{aligned}$$

Aim: Show that \tilde{u} is bounded knowing that \tilde{g} is bounded. Use that k satisfies

$$k(t,s)=0 \quad ext{for } s\geq t, \qquad \|k\|:=\sup_t \int_{\mathbb{R}^+} |k(t,s)|\,\mathrm{d} s<\infty.$$

This forms a Banach algebra for products

$$k_1 \star k_2(t,s) = \int_{\tau=0}^{\infty} k_1(t,\tau) k_2(\tau,s) \,\mathrm{d} au$$

Phase mixing for $v \in \mathbb{S}^d$ 0000000 In this algebra, find the resolvent r satisfying

$$r + r \star k = r + k \star r = k.$$

If k has a resolvent the solution is $\tilde{u} = \tilde{g} - r \star \tilde{g}$. Obtain the resolvent for small enough ϵ as perturbation from a von Neumann series of the kernel $K(t-s)\mathbf{1}_{s < t}$ which has a resolvent $R(t-s)\mathbf{1}_{s < t}$.

Last point: Spectral condition (Lap) Use complex analysis for a Penrose style argument. Here one studies the winding number of $det(I + \mathcal{LK})$.

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Theorem

Let $s > \frac{7}{2}$. Assume linear stability. $\exists C_0, \nu_0, \delta_0 > 0$ such that $\forall \nu \leq \nu_0$ and all initial data ψ^{in}

$$\|\psi^{in}\|_{H^s_x L^2_p} \le \delta_0 \nu^{\frac{3}{2}}$$

there exists a global solution ψ satisfying

$$\sup_{t\geq 0} \|\psi(t)\|_{H^{s}_{x}L^{2}_{p}}^{2} + \nu \int_{0}^{\infty} \|\nabla_{p}\psi(t)\|_{H^{s}_{x}L^{2}_{p}}^{2} \,\mathrm{d}t \leq C_{0}\,\nu^{-1}\|\psi^{in}\|_{H^{s}_{x}L^{2}_{p}}^{2}.$$

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Phase mixing for $v \in \mathbb{S}^{d}$

Recall full equation:

$$\begin{cases} \partial_t f + (v+u) \cdot \nabla_x f + \nabla_v \cdot \left(\mathbb{P}_{v^{\perp}} \left[(\gamma E(u) + W(u)) v \right] f \right) = \nu \Delta_v f, \\ -\Delta_x u + \nabla_x q = \alpha \nabla_x \cdot \int_{\mathbb{S}^2} f(t, x, v) \, v \otimes v \, \mathrm{d}v, \\ \nabla_x \cdot u = 0. \end{cases}$$

Main difficulty: Cannot treat $u \cdot \nabla_x f$ as error term in linear theory (x regularity)

- Need to use $\nabla \cdot u = 0!$
- Need to take all modes together

Advection-diffusion equation

Given velocity field v with (bootstrap) assumption

$$\sup_{t\geq 0} \|v(t)\|_{H^{s}} + \left(\int_{0}^{\infty} \|v(t)\|_{H^{s}}^{2} \mathrm{d}t\right)^{\frac{1}{2}} \leq \epsilon \nu^{\frac{5}{4}} \tag{H}$$

Evolution

$$\partial_t g + (v + p) \cdot \nabla_x g = \nu \Delta_p g.$$

Theorem

Let
$$s > \frac{5}{2}$$
, $0 < s' < s + \frac{1}{4}$. $\exists C_0, \epsilon, \nu_0, \eta_1 > 0$. For $\nu \le \nu_0$:

$$\begin{split} \|g(t)\|_{H^s_x L^2_p} &\leq C_0 \mathrm{e}^{-\eta_1 \nu^{\frac{1}{2}} t} \|g^{\mathrm{in}}\|_{H^s_x L^2_p}, \\ \sum_{k \neq 0} |k|^{2s'} |V_k[g_k(t)]|^2 &\lesssim \left(\frac{\nu^{\frac{1}{2}}}{\min\{1, \nu^{\frac{1}{2}}t\}}\right)^3 \|g^{\mathrm{in}}, \nabla_p g^{\mathrm{in}}, \nabla_p^2 g^{\mathrm{in}}\|_{H^s_x L^2_p}^2. \end{split}$$

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Ideas for the advection-diffusion equation

Study each Fourier mode k: Need long time results for enhanced dissipation and mixing (with localisation). For enhanced dissipation, functional for mode k

$$E_{\chi,k}(Y_k) = \|Y_k\chi\|^2 + \left(\frac{\nu}{|k|}\right)^{\frac{1}{2}} a_k \|\nabla_p Y_k\chi\|^2 \\ + 2b_k \Re \langle i\nabla_p (p \cdot \hat{k}) Y_k\chi, \nabla_p Y_k\chi \rangle \\ + \left(\frac{\nu}{|k|}\right)^{-\frac{1}{2}} c_k \|\nabla_p (p \cdot \hat{k}) Y_k\chi\|^2$$

where $(a_k, b_k, c_k) := (a, b, c)(h)$ with $h = \nu^{\frac{1}{2}} |k|^{\frac{1}{2}} t$ and $a(h) = A \min(h, 1), \quad b(h) = B \min(h^2, 1), \quad c = C \min(h^3, 1).$

Covering the advection

Use summed quantity:

$$E_{\chi,s}(Y) = \sum_{k} |k|^{2s} E_{\chi_k,k}(Y_k)$$

Simplified typical error term from velocity field v (no localisation):

$$\begin{split} &\sum_{k,\ell} |k|^{2s} \Re \langle i k v_{k-\ell} Y_{\ell}, Y_{k} \rangle \\ &= \frac{1}{2} \sum_{k,\ell} \Re \langle i \left(|k|^{2s} k - |\ell|^{2s} \ell \right) \cdot v_{k-\ell} Y_{\ell}, Y_{k} \rangle \\ &= \frac{1}{2} \sum_{k,\ell} \Re \langle i \left(|k|^{2s} - |\ell|^{2s} \right) v_{k-\ell} \cdot \ell Y_{\ell}, Y_{k} \rangle \end{split}$$

Use the gain from the difference.

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