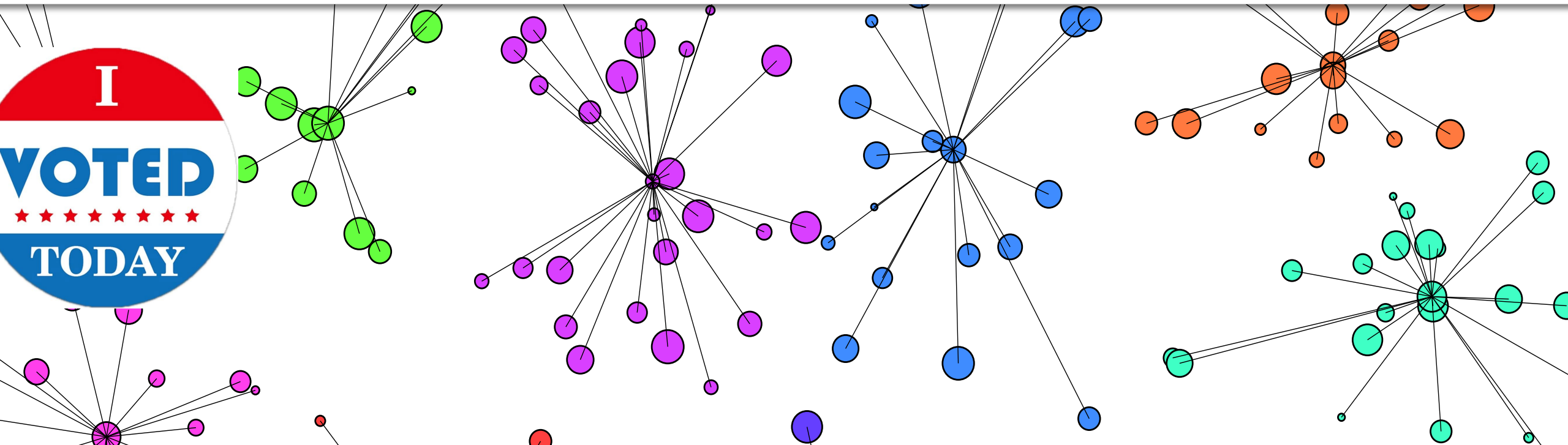


Ballot Clustering Algorithms

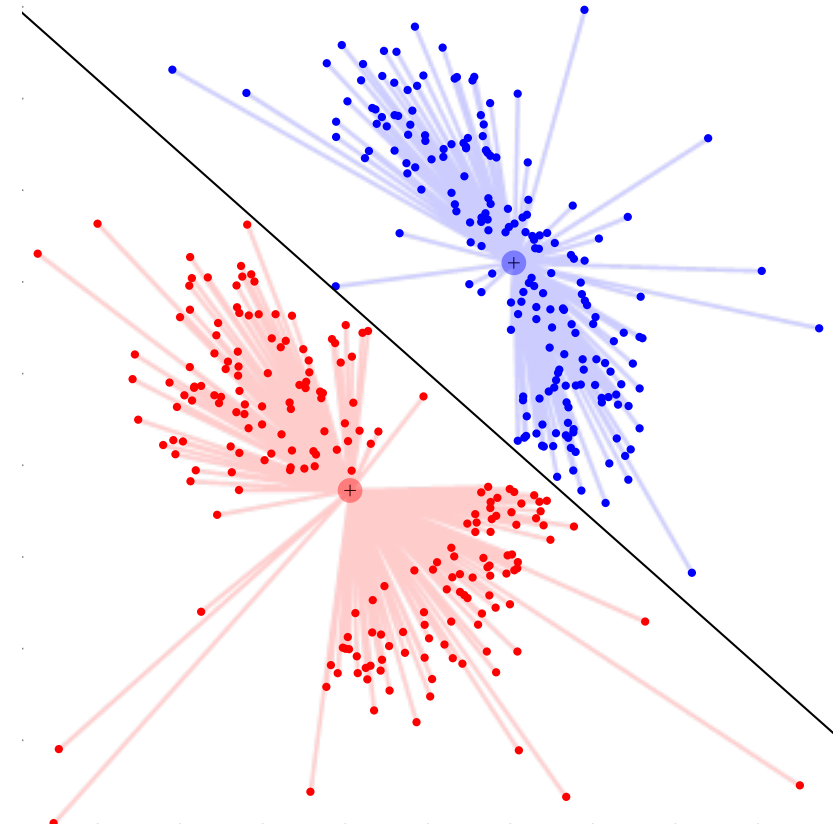
Kristopher Tapp, Saint Joseph's University

joint with Moon Duchin & David Shmoys



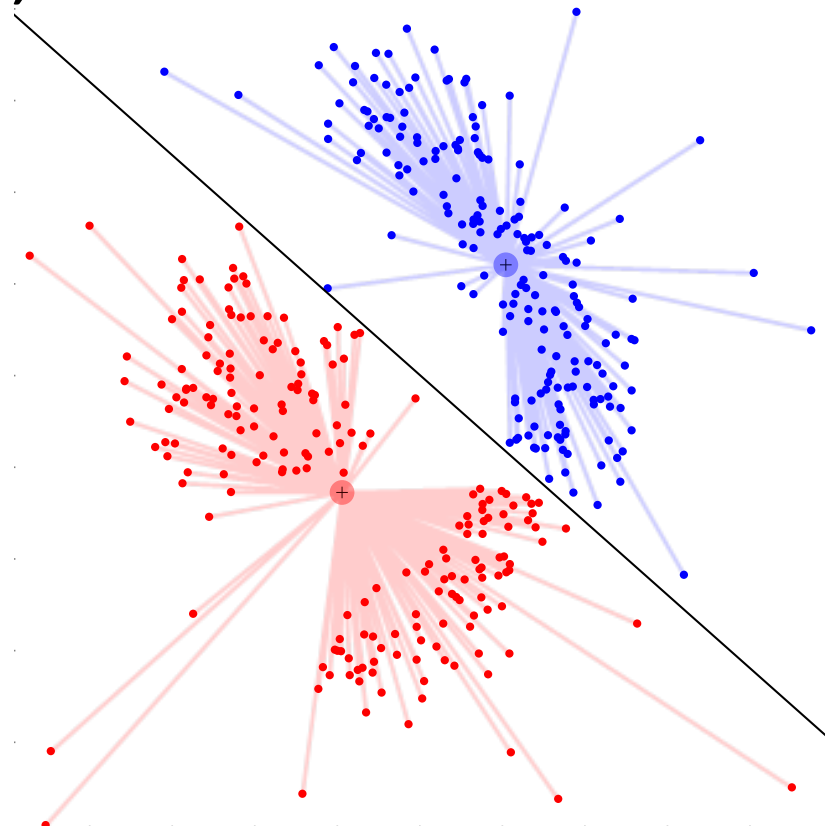
There are standard algorithms to cluster points of Euclidean space.

What about ranked choice ballots?



**Edinburgh Ward 2 (Petland Hills): 7 candidates, 11315 ballots,
1238 distinct ballots.**

1342 votes for (1, 6).
759 votes for (6, 1).
578 votes for (3, 5).
494 votes for (4).
403 votes for (3, 5, 7).
285 votes for (1, 6, 2).
254 votes for (1, 6, 4).
219 votes for (5, 3).
173 votes for (4, 2).
152 votes for (6, 1, 4).
144 votes for (5, 3, 7).
136 votes for (1, 6, 4, 2).
136 votes for (3, 5, 4)...



1=Graeme Bruce (C), 2 = Emma Farthing (LD), 3 = Neil Gardiner (SNP), 4 = Ricky Henderson (Lab), 5 = Ernesta Noreikiene (SNP), 6= Susan Webber (C), 7 = Evelyn Weston (Grn).

PROXY CLUSTERING: Associate each ballot to a proxy point of Euclidean space, and perform a standard clustering algorithm on the proxies.

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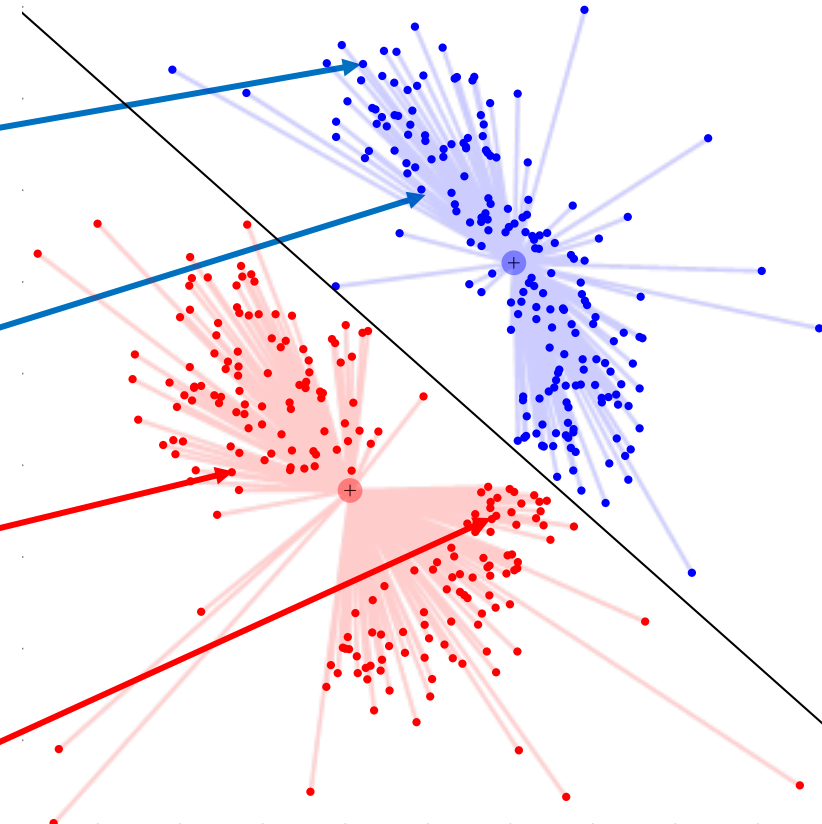
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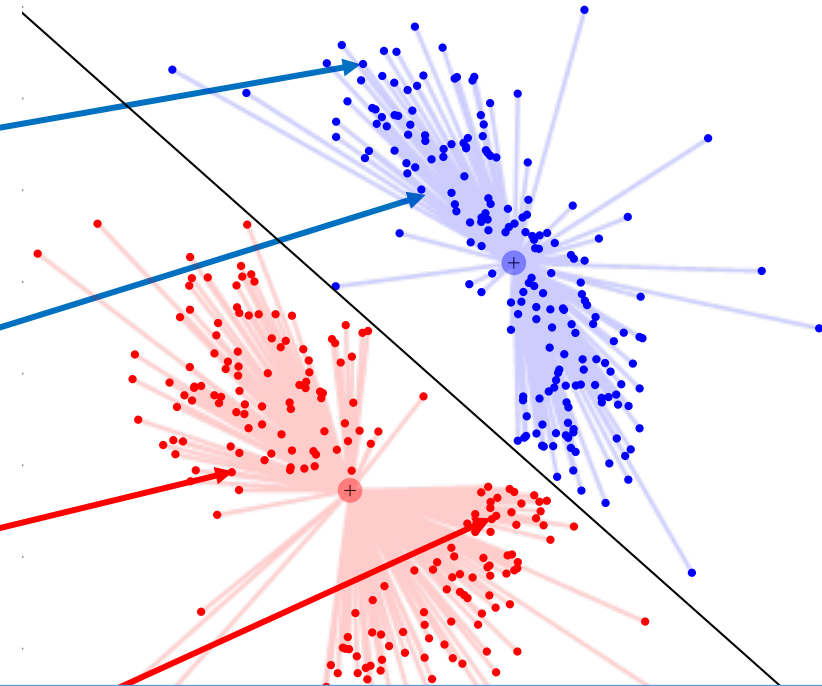
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* Any number of clusters is allowed.

* The distance between proxies must correspond to some natural measurement of ballot similarity.

SLATE CLUSTERING: Find the partition of the candidates into two slates A,B such that the ballots are most starkly divided into “A>B types” and “B>A types”. Partition the ballots accordingly.

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SLATE A:

3 = Neil Gardiner (SNP)

5 = Ernesta Noreikiene (SNP)

7 = Evelyn Weston (Grn)

SLATE B:

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2 = Emma Farthing (LD)

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- Always forms 2 clusters
- Good for studying polarized elections

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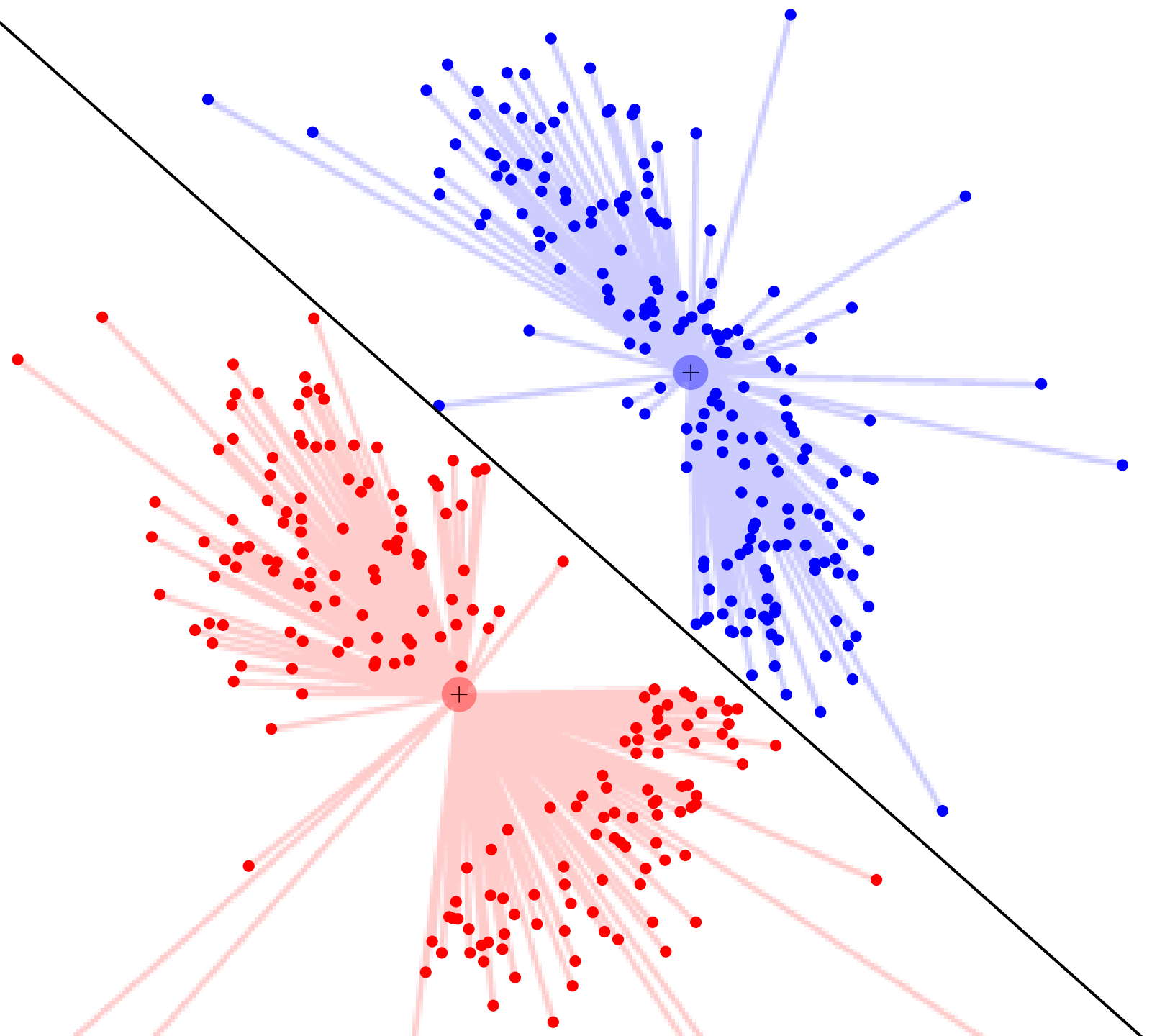
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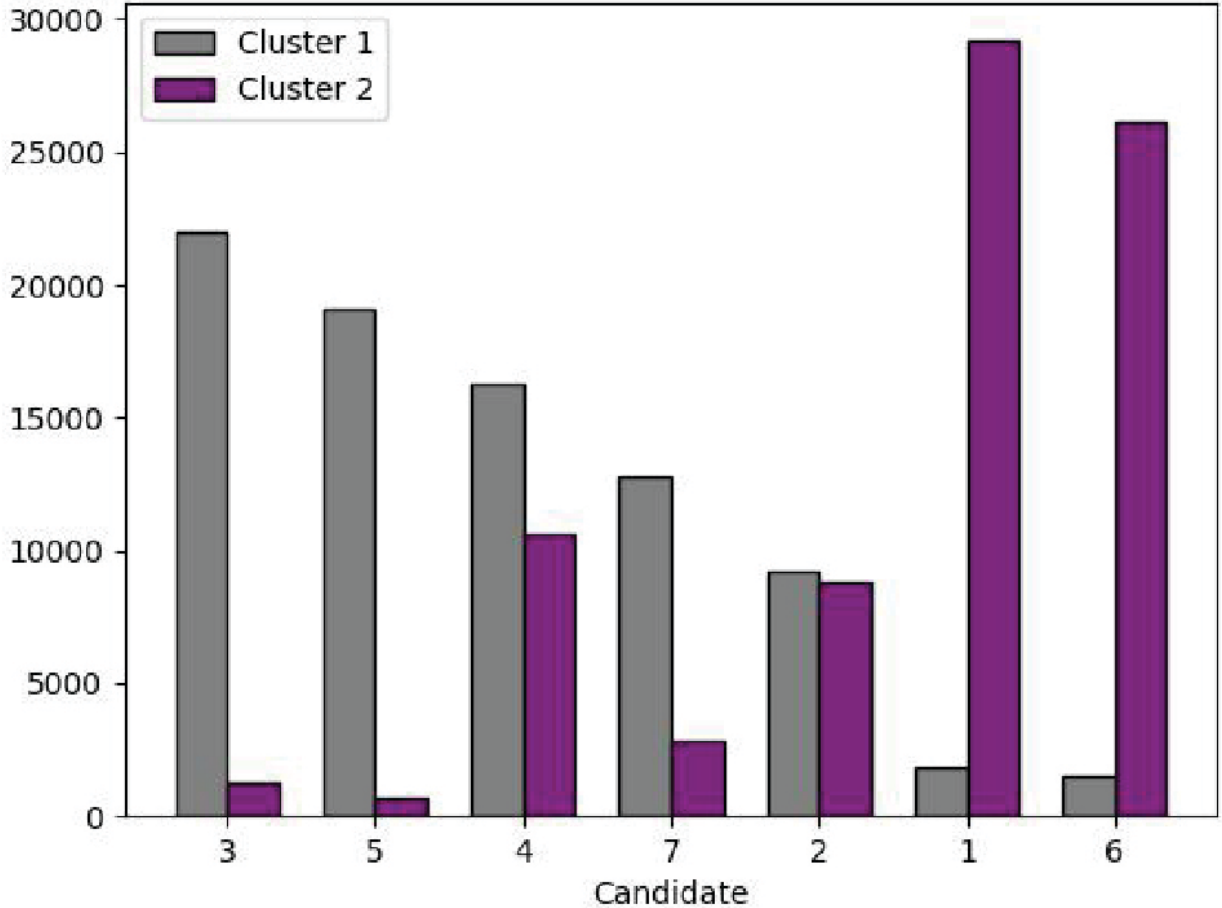
- Always forms 2 clusters
- Good for studying polarized elections
- How should we sort (3,2,4,7)?

Visualizing clusters



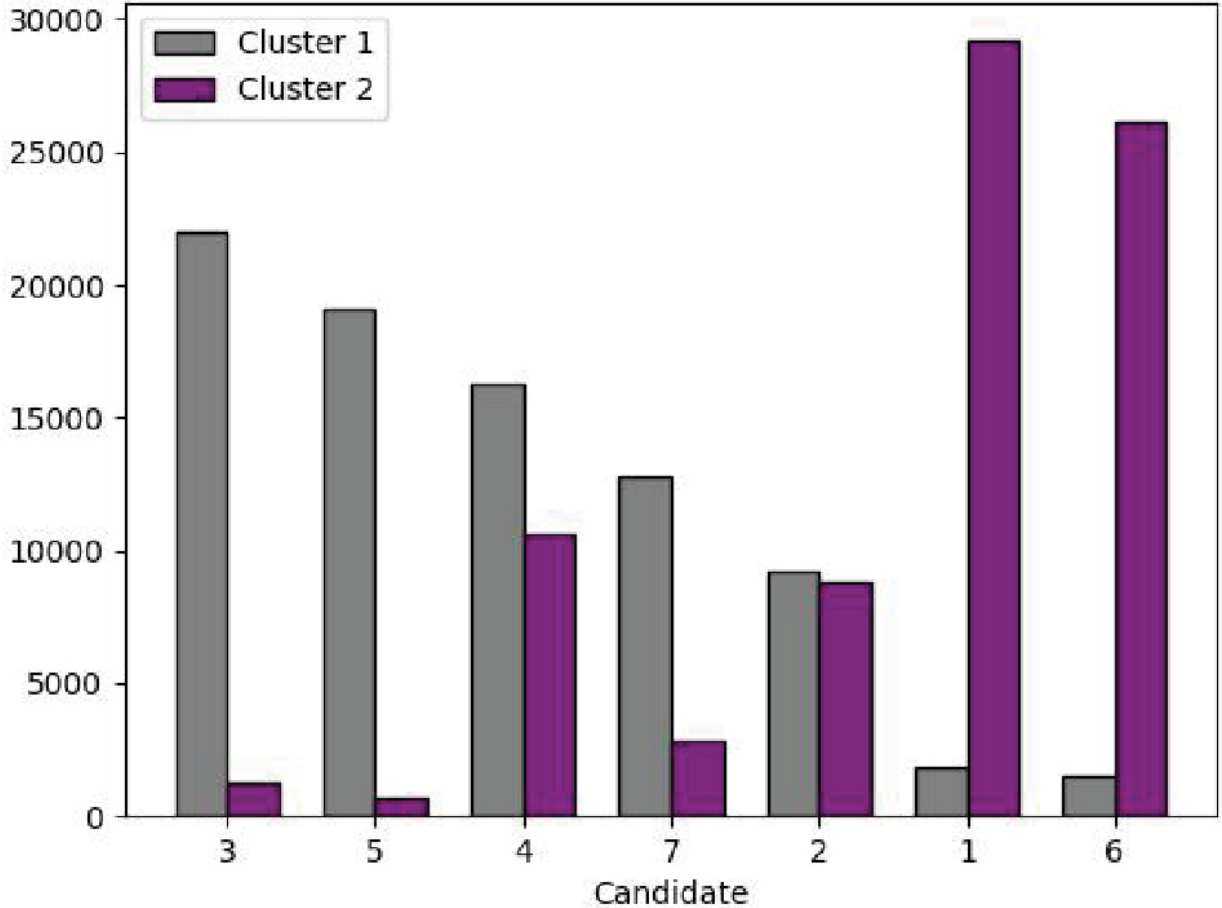
Proxy clustering (with Borda proxies and k-means)

Borda Scores of Candidates by Cluster

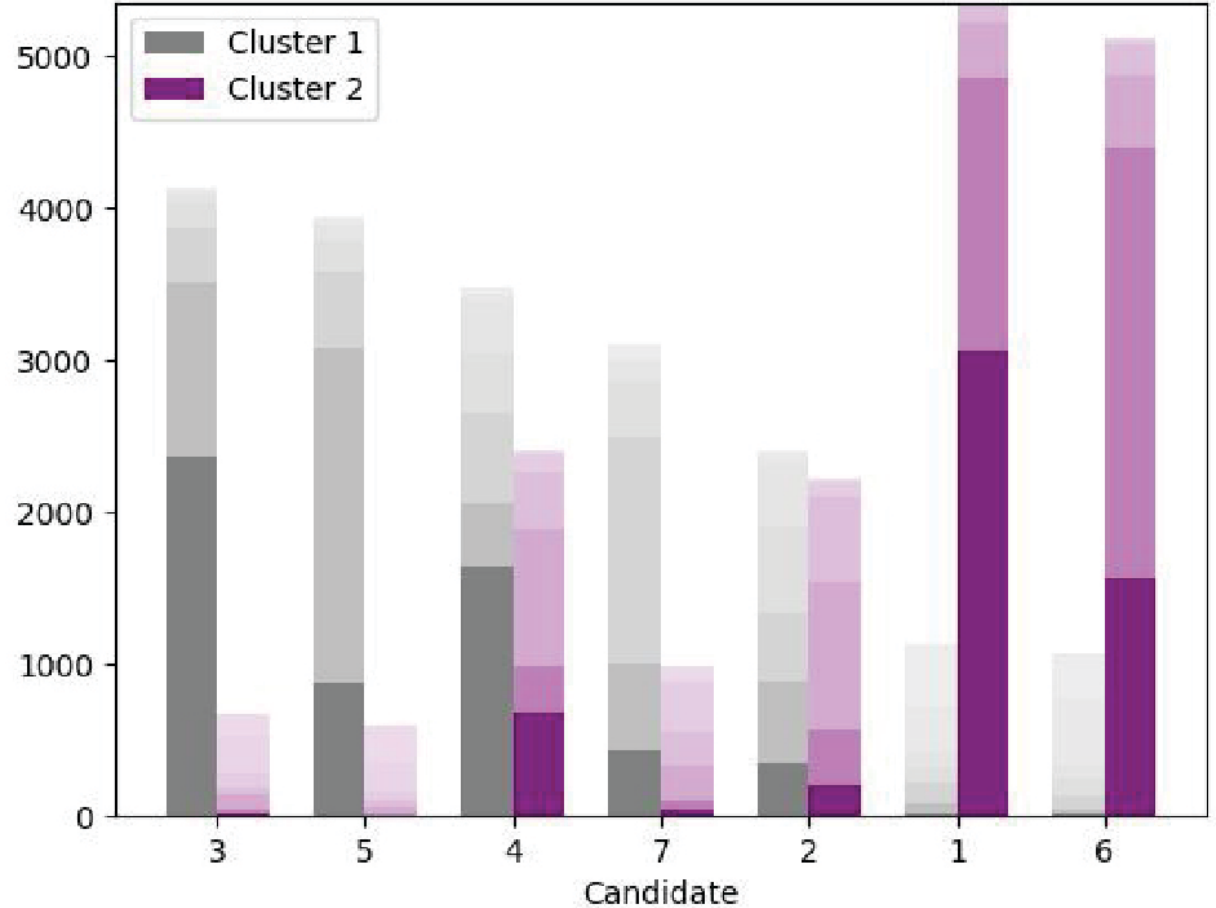


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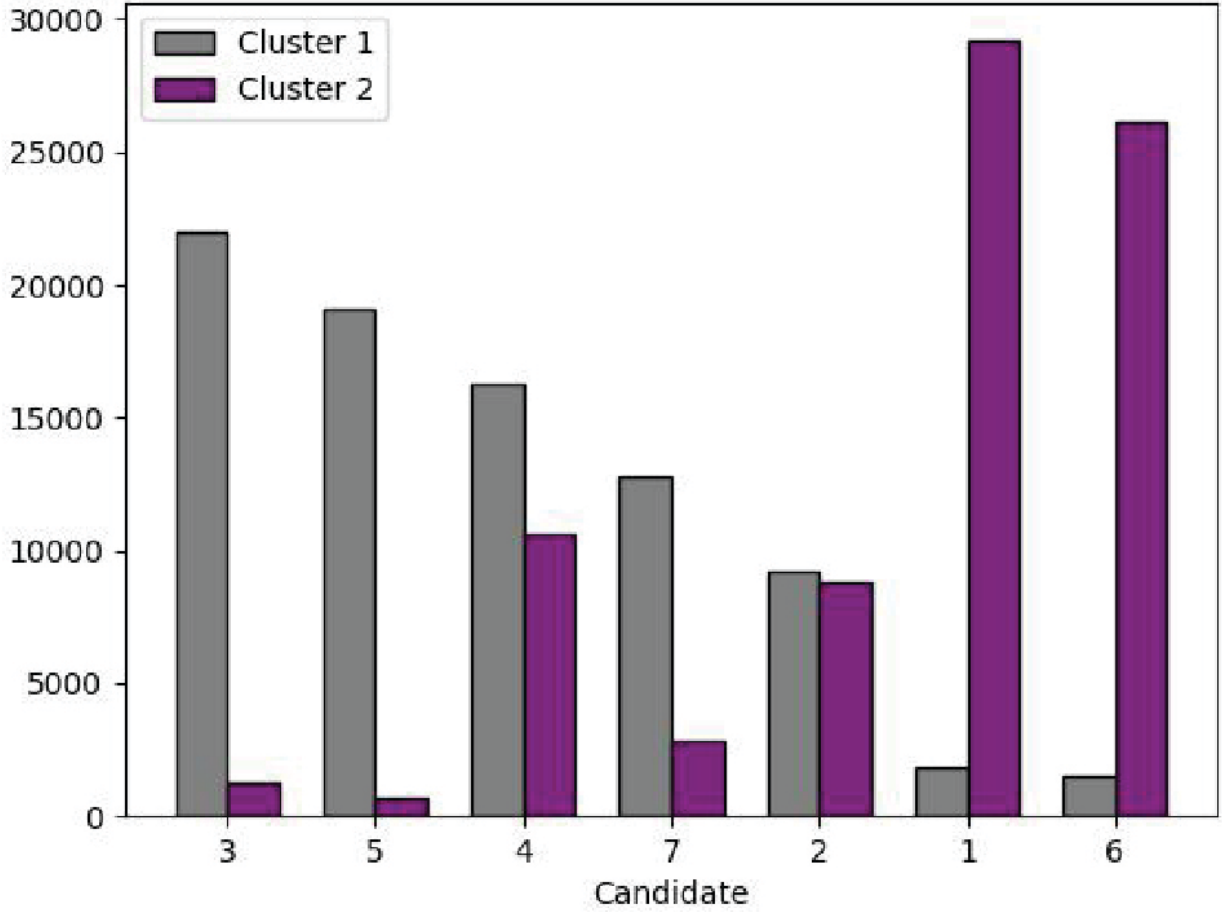


Candidate Mentions Stacked by Ballot Position

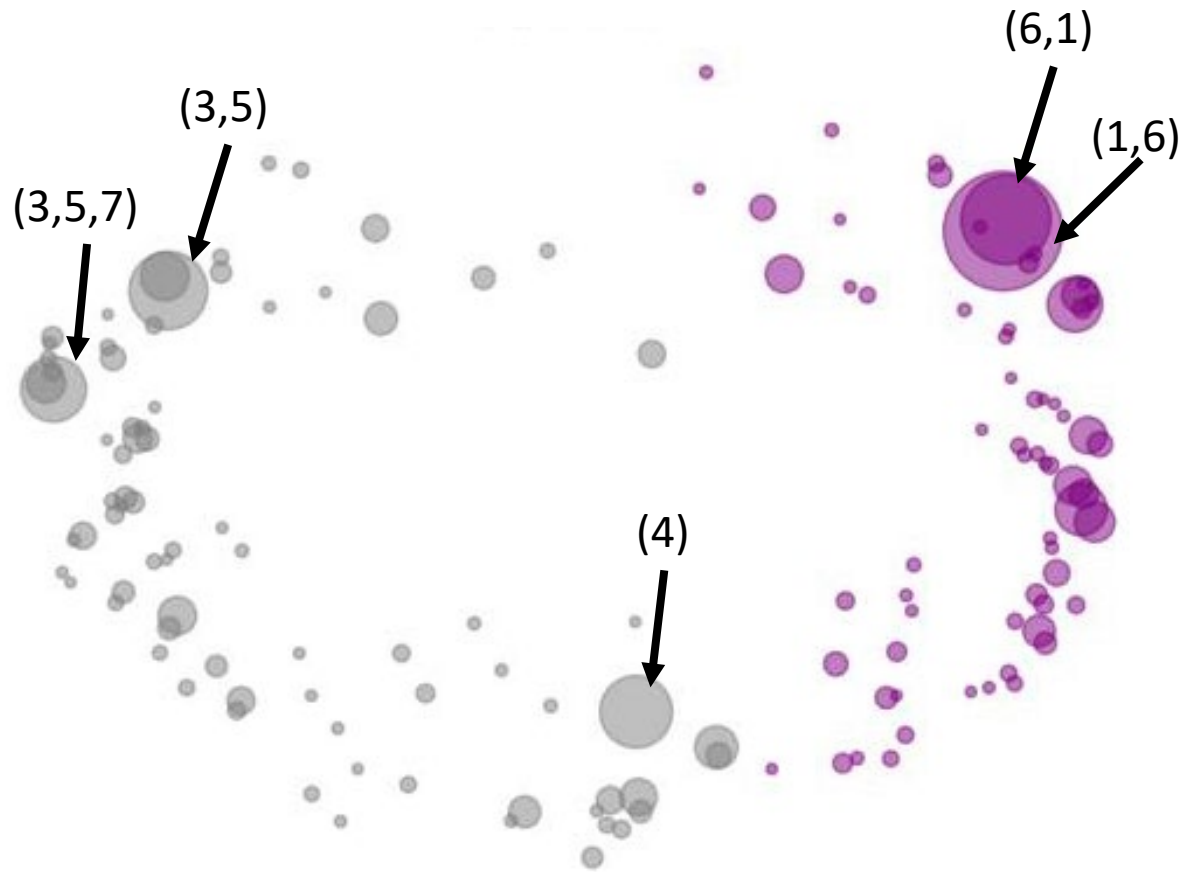


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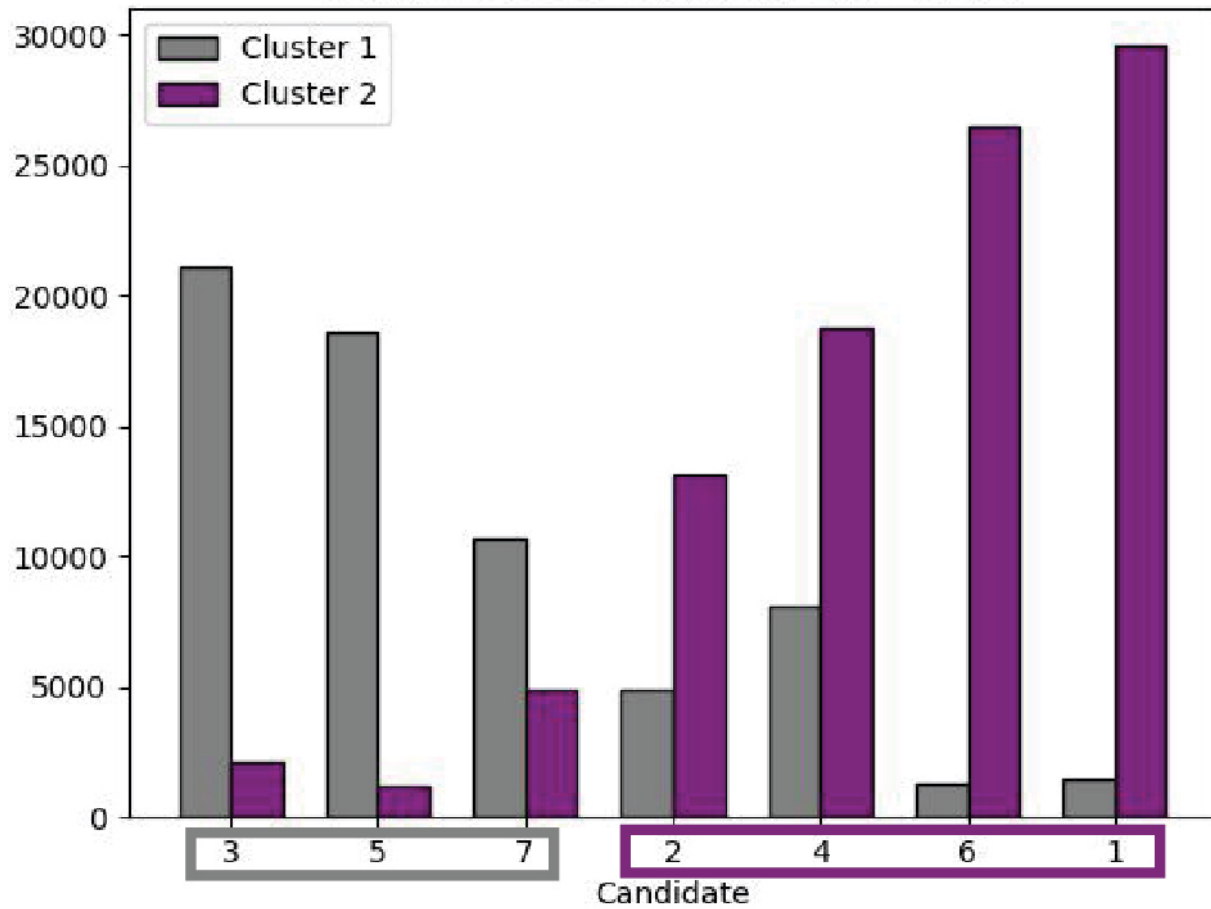


MDS Plot of ballots with more than 10 votes.

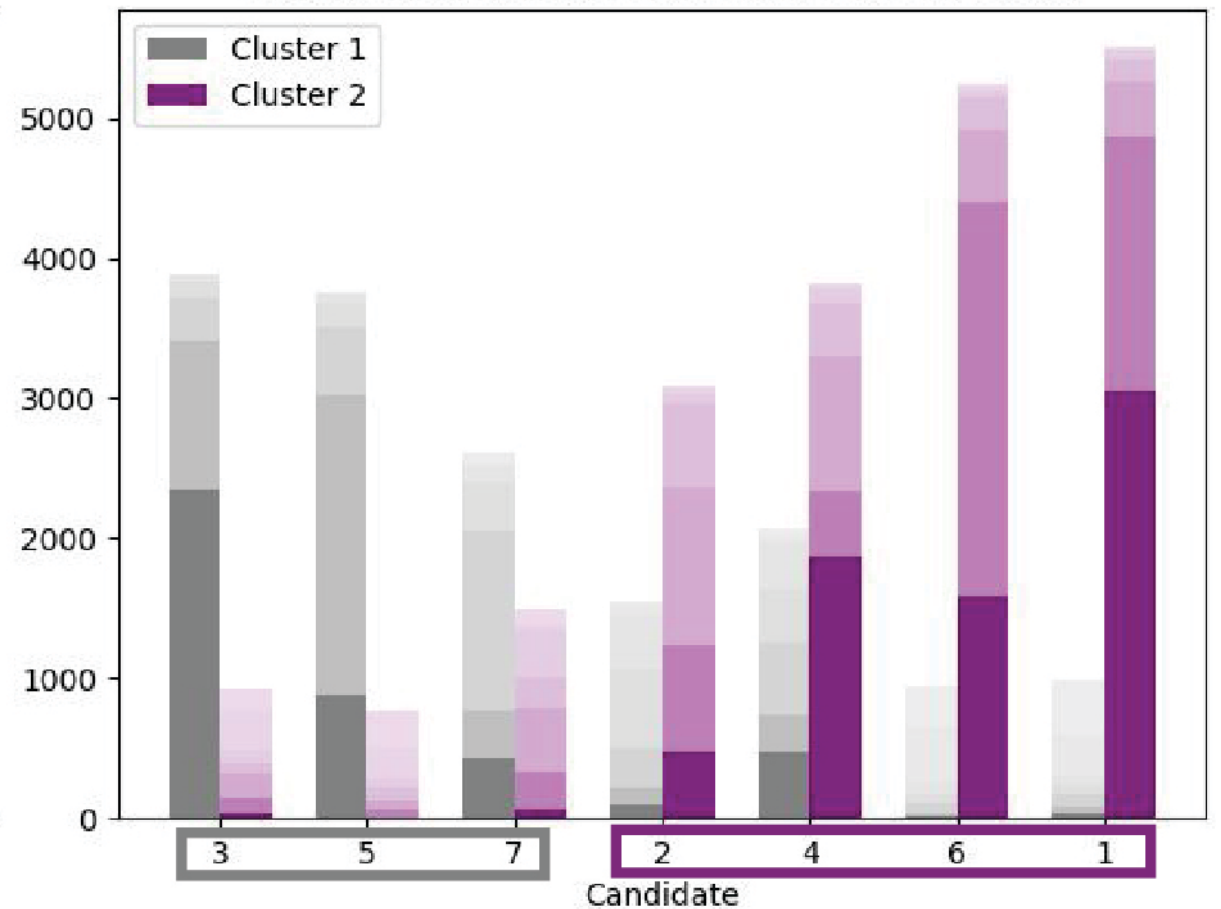


Slate clusters

Borda Scores of Candidates by Cluster



Candidate Mentions Stacked by Ballot Position



GOAL: Find a *good* metric on $\Omega_n =$ the set of possible ballots on n candidates.

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- Generalizable to ballots that allow ties.

like: $(\{A_1, A_2\}, \{B_1, B_2, B_3\}, \{C_1, C_2, C_3\})$

Unmentioned candidates are group last

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or like: SLATE A > SLATE B.

GOAL: Find a *good* metric on $\Omega_n =$ the set of possible ballots on n candidates.

WISH LIST:

- Interpretable as a natural and intuitive “similarity” of the ballots.
- Realizable as the distance between proxy points in coordinate space.
- Generalizable to ballots that allow ties.
- Based on familiar concepts like head-to-head comparisons or Borda points.

GOAL: Find a *good* metric on Ω_n = the set of possible ballots on n candidates.

WE'LL STUDY TWO METRICS:

- d_H = head-to-head distance

- d_B = Borda distance

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- d_H = head-to-head distance
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= *shift count*
= *distance between Borda proxies*
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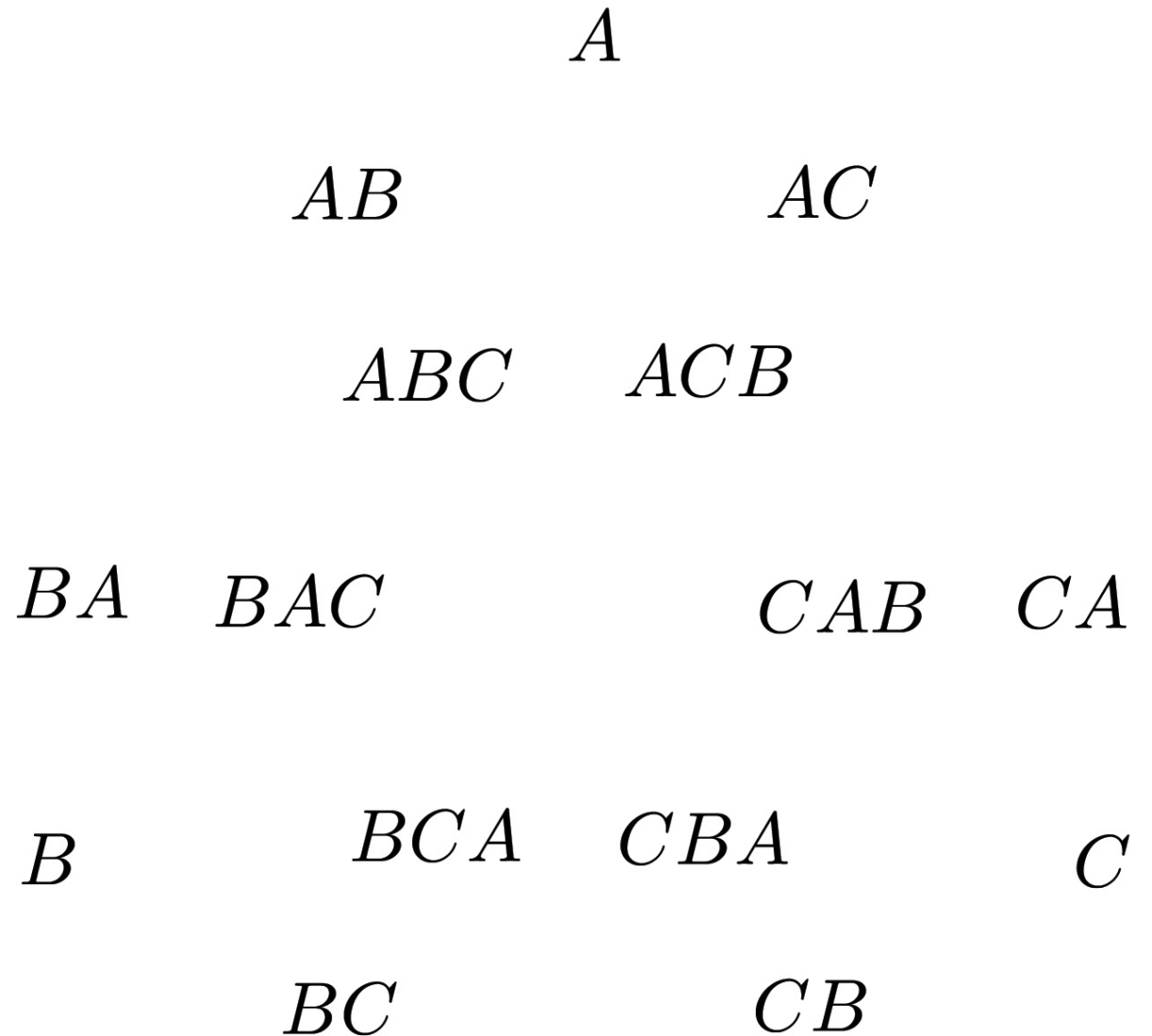
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And we'll show that d_H and d_B are very similar.

The Ballot Graph

The Ballot Graph

- Nodes = all possible ballots



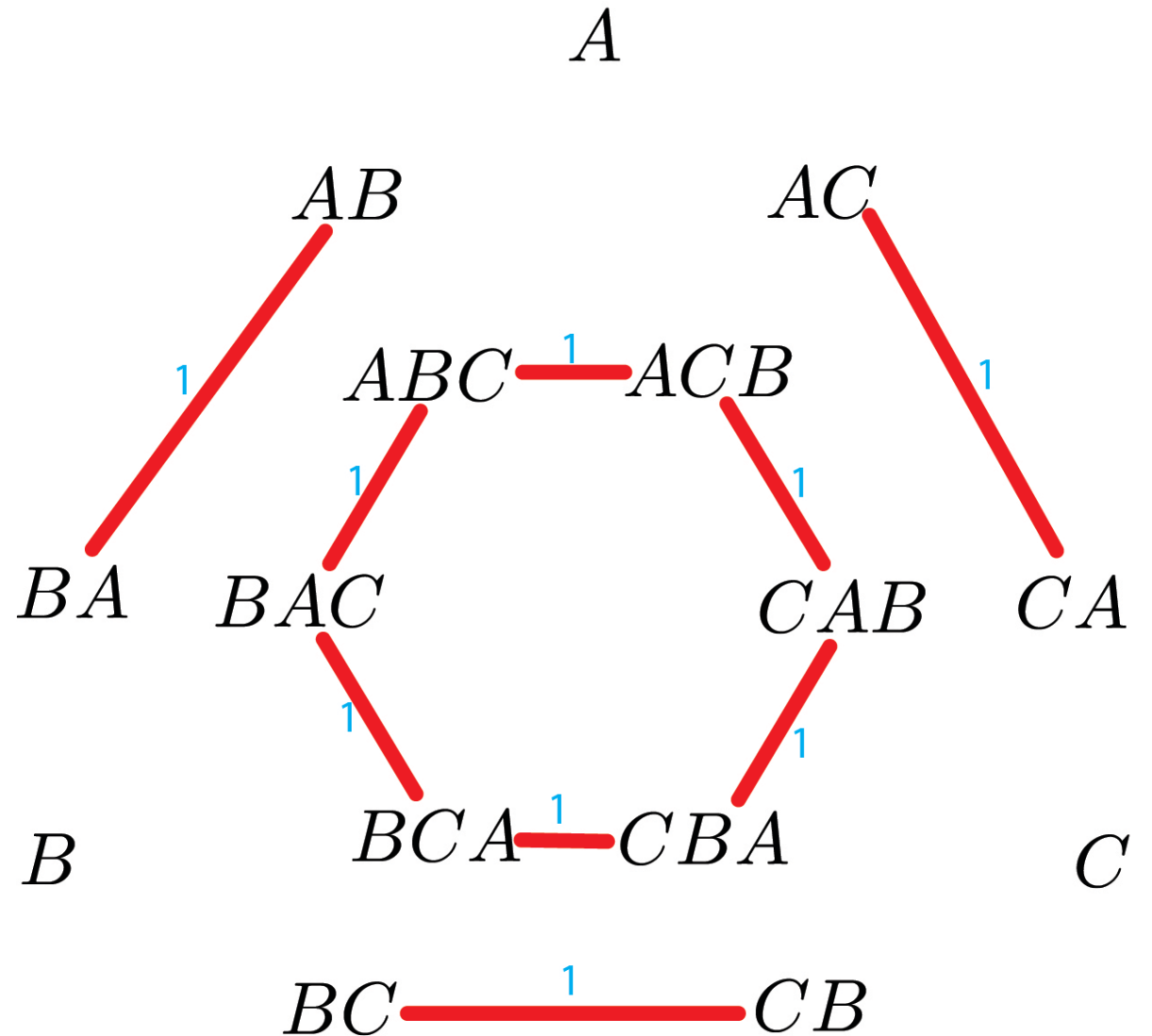
The ballot graph for Ω_3

The Ballot Graph

- Nodes = all possible ballots
- An edge of weight 1 if related by an adjacent swap.

Example:

$ABCDEF \xrightarrow{1} ABDCEF$ in Ω_7



The ballot graph for Ω_3

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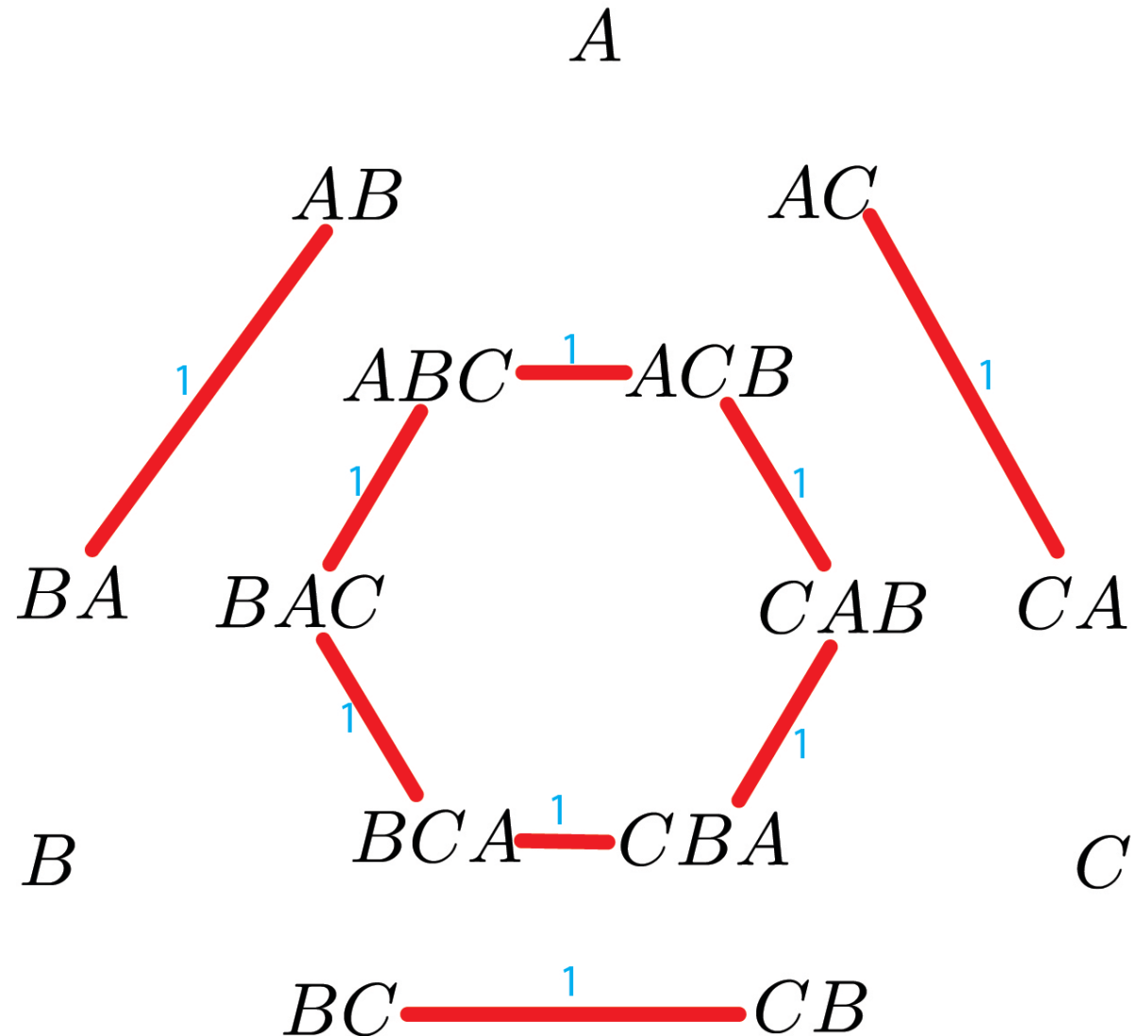
- An edge if related by removing/adding final candidate.

$$\text{Weight} = \frac{\# \text{ missing}}{2}$$

Example:

AB**** --- ABC*** in Ω_6

has weight $\frac{3}{2}$



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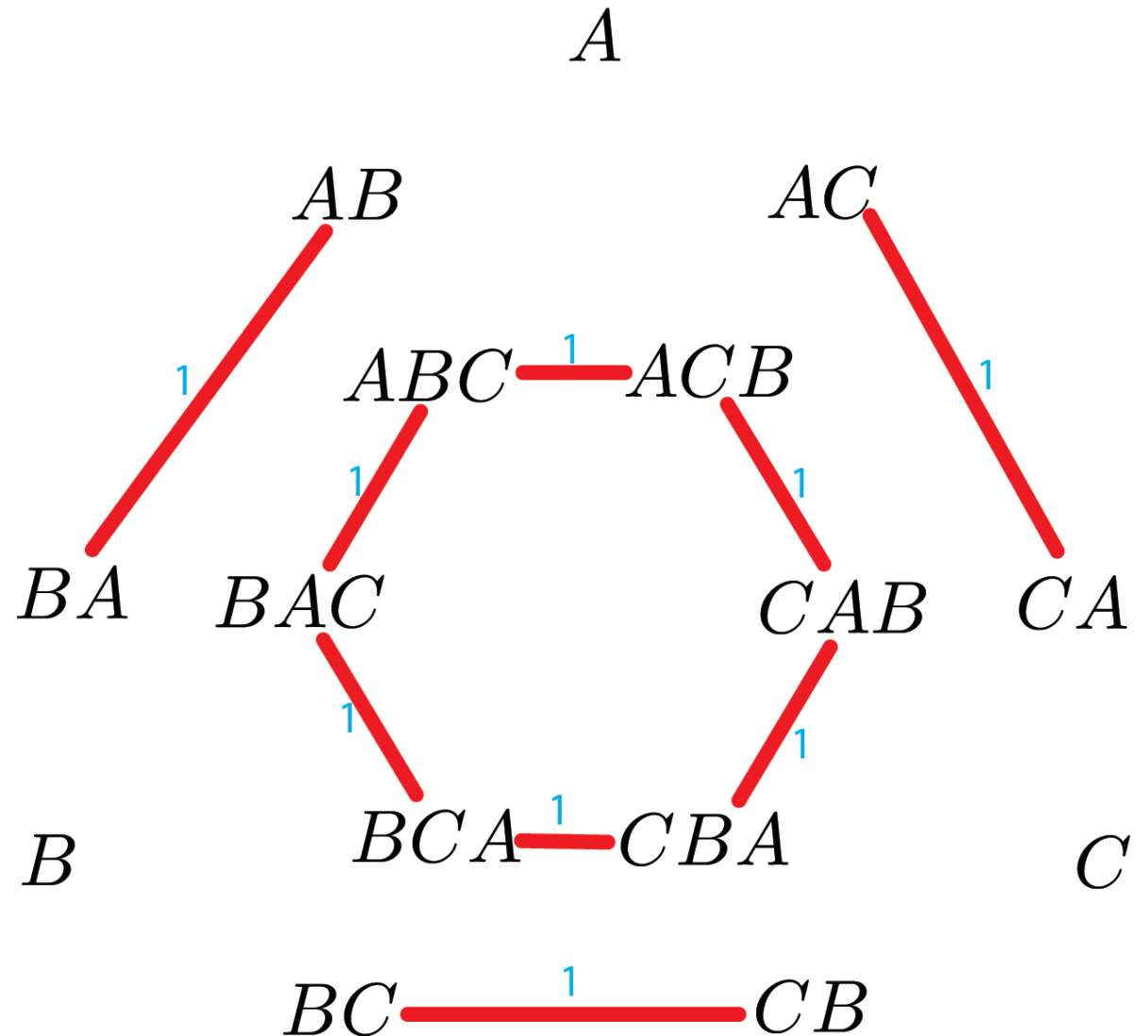
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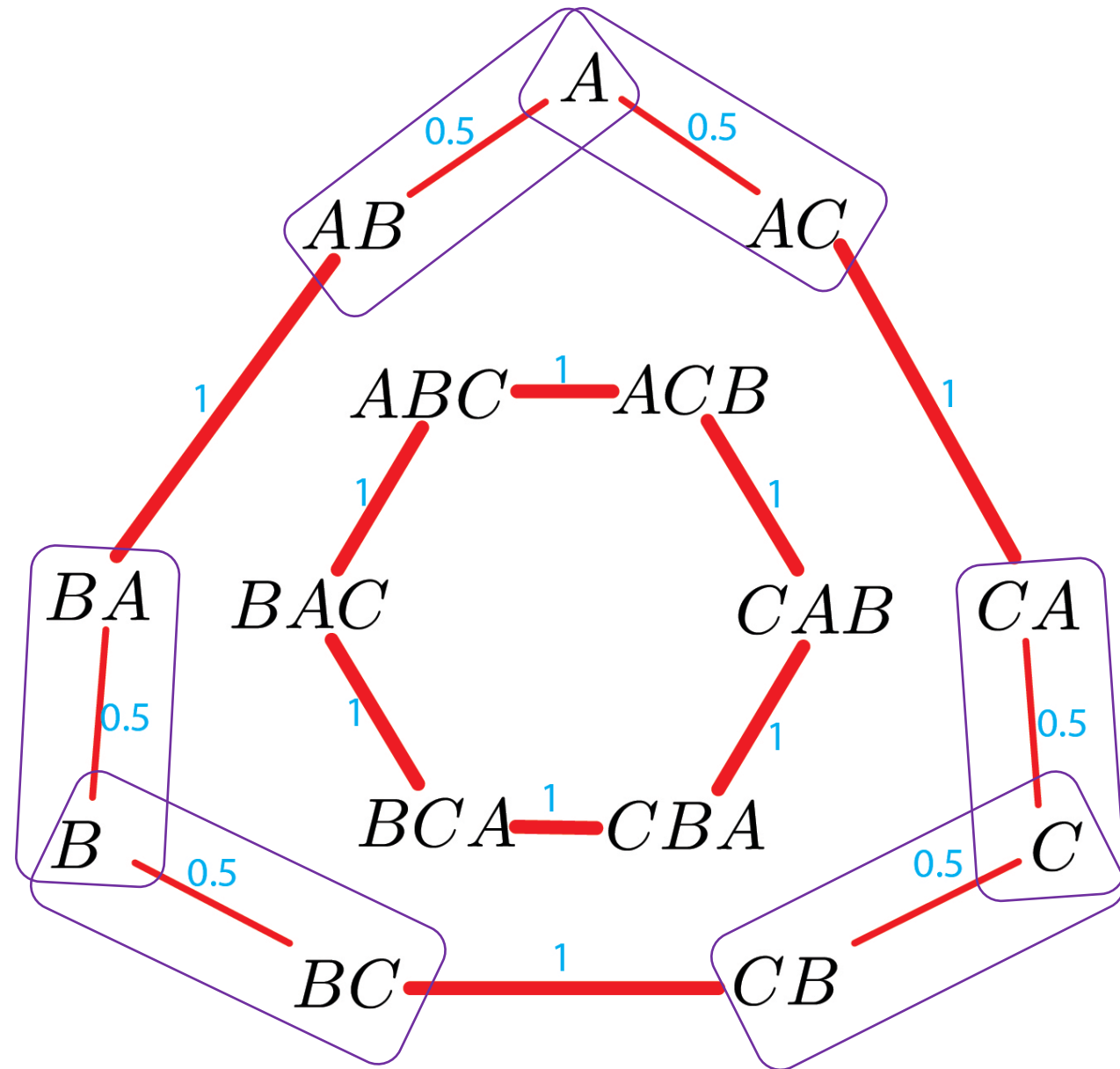
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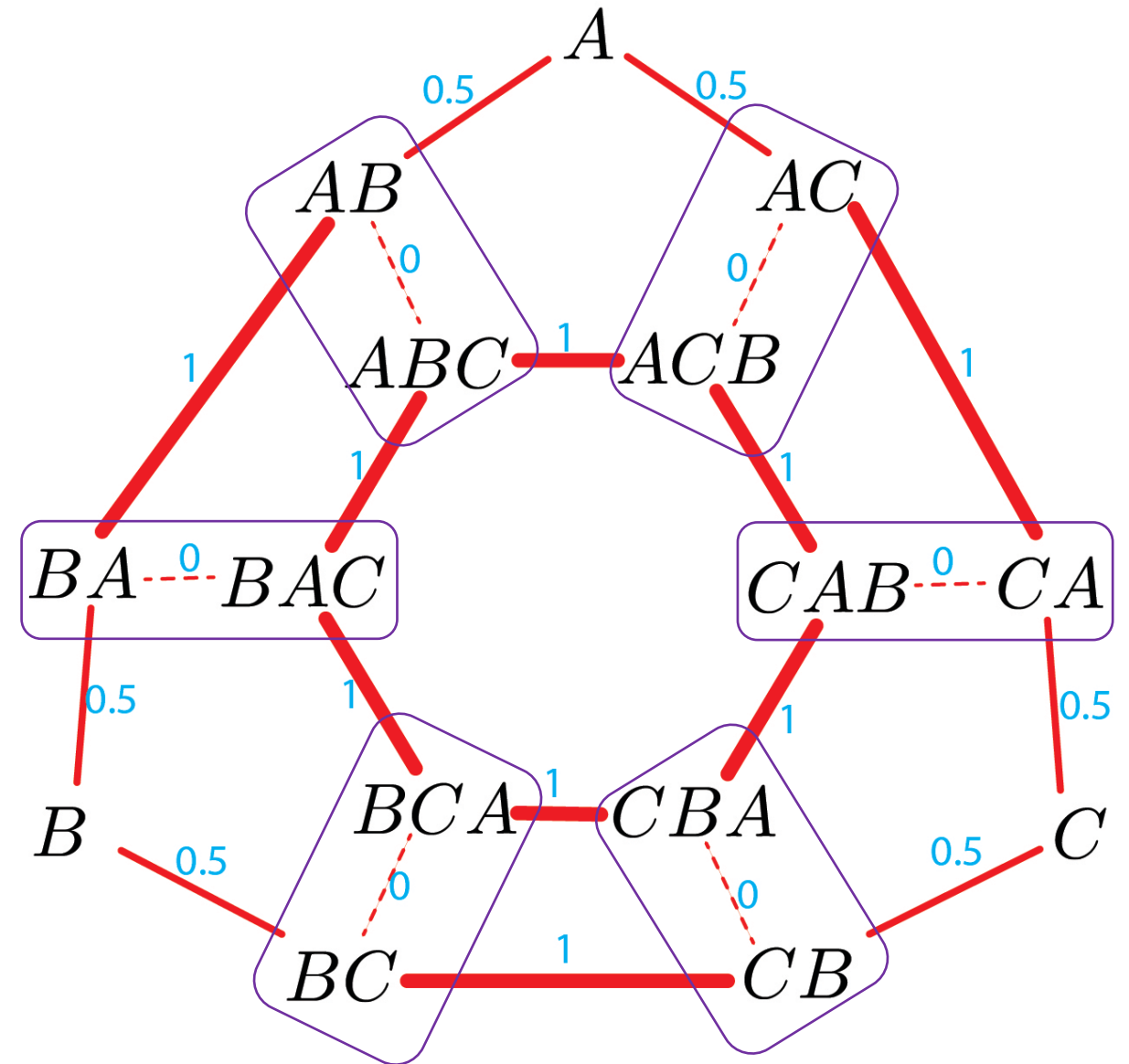
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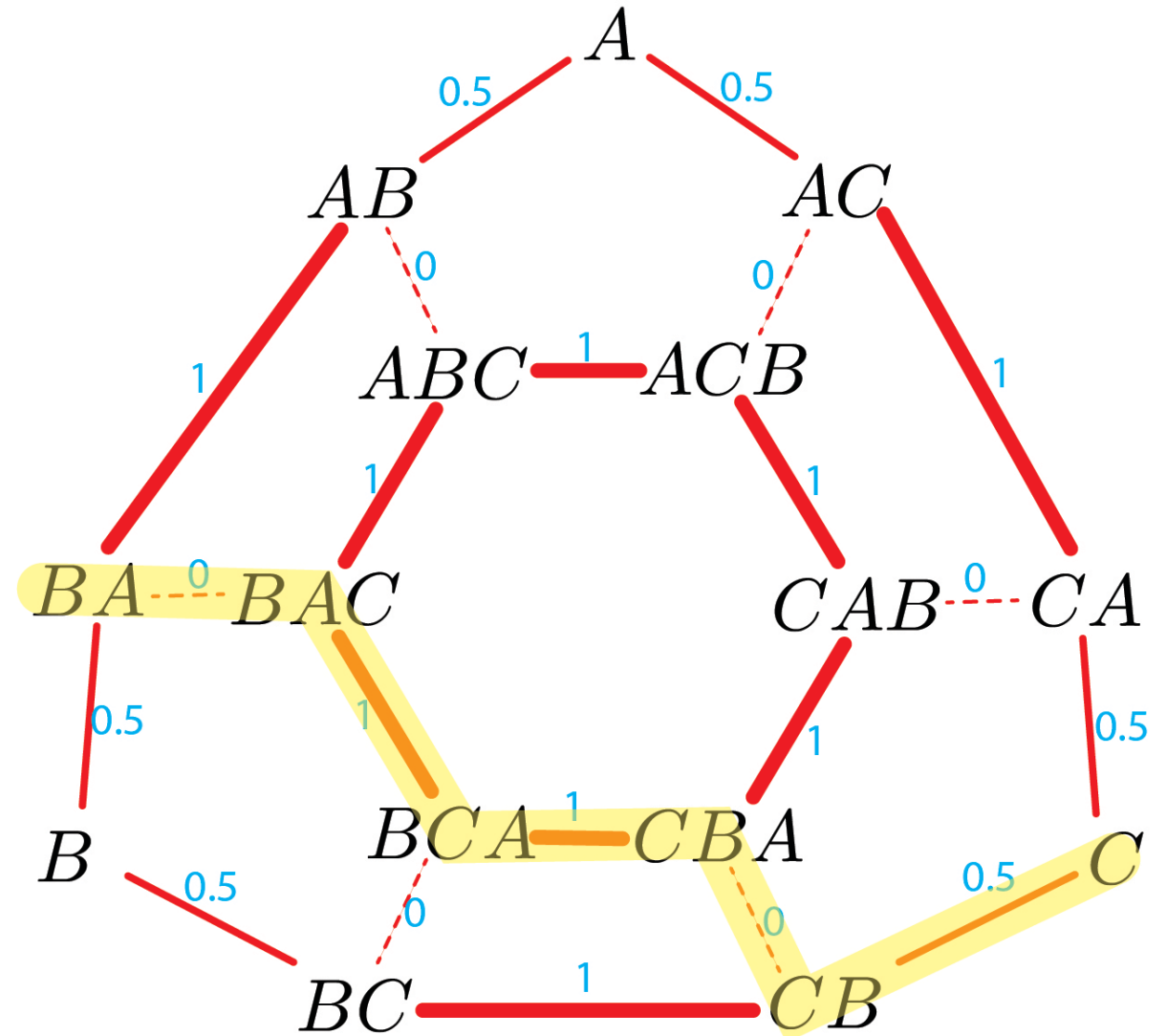
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Distance from **BA** to **C** = 2.5



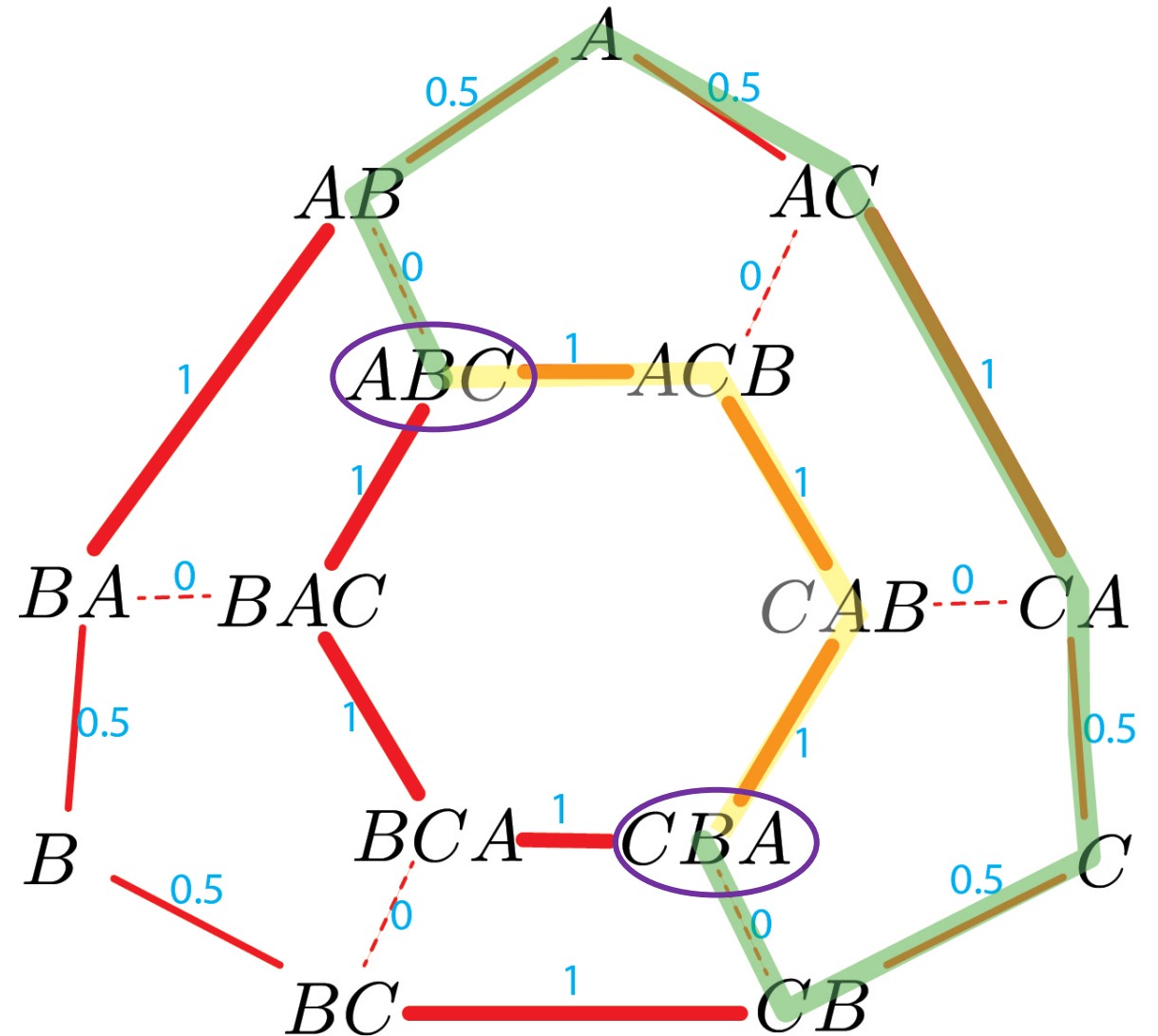
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Between a *complete* ballot and its reversal, the bullet path ties.



The ballot graph for Ω_3

The weighted disagreement count

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Consider the ballots **ACB** and **AE** in Ω_5 .

Among the 10 comparisons:

AB, AC, AD, AE, BC, BD, BE, CD, CE, DE

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So, distance from **ACB** to **AE** = *strong* + $\frac{1}{2} \cdot \textit{weak}$ = 2 + $\frac{1}{2} \cdot 4$ = 4.

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So, distance from **ACB** to **AE** = *strong* + $\frac{1}{2} \cdot$ *weak* = 2 + $\frac{1}{2} \cdot 4 = 4$.

(We'll see that the $\frac{1}{2}$ weighting convention makes this a valid metric.)

The head-to-head proxy distance

The head-to-head proxy distance

In Ω_5 , head-to-head proxies are in 10-dimensional space.
The proxy of **ACB** is:

KEY:

.5 = win

-.5 = lose

0 = tie

	AB	AC	AD	AE	BC	BD	BE	CD	CE	DE
ACB	.5	.5	.5	.5	-.5	.5	.5	.5	.5	0

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ACB	.5	.5	.5	.5	-.5	.5	.5	.5	.5	0
AE	.5	.5	.5	.5	0	0	-.5	0	-.5	-.5
<i>dif</i> =	0	0	0	0	-.5	.5	1	.5	1	-.5

$d_H(\mathbf{ACB}, \mathbf{AE})$ = the Manhattan distance between their proxies = $2 + \frac{4}{2} = 4$.

The head-to-head proxy distance

Proposition 4.1. *For $\mathcal{B}_1, \mathcal{B}_2 \in \Omega_n$, the following are equivalent definitions of $d_H(\mathcal{B}_1, \mathcal{B}_2)$.*

- 1. The ballot graph distance*
- 2. The Manhattan distance between their head-to-head proxies.*
- 3. The weighted disagreement count.*

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The proposition generalizes to ballots that allow ties, like this

	AB	AC	AD	AE	BC	BD	BE	CD	CE	DE
$(\{A, E\}, \{B, C, D\})$.5	.5	.5	0	0	0	-.5	0	-.5	-.5

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1. The ballot graph distance

How is this defined for generalized ballots?

2. The Manhattan distance between their head-to-head proxies.

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The generalized ballot graph

Half the product of the sizes of the merged sets

$$(\{A_1, A_2\}, \{B_1, B_2, B_3\}, \{C_1, C_2\}, \{D\}) \xrightarrow{\frac{6}{2}} (\{A_1, A_2\}, \{B_1, B_2, B_3, C_1, C_2\}, \{D\})$$

The generalized ballot graph

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Adjacent candidate swaps have weight 1, as before:

$$(\{A_1, A_2\}, \{B\}, \{C\}, \{D\}) \xrightarrow{\frac{1}{2}} (\{A_1, A_2\}, \{B, C\}, \{D\}) \xrightarrow{\frac{1}{2}} (\{A_1, A_2\}, \{C\}, \{B\}, \{D\})$$

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and truncation has the same weight as before:

$$(\{A_1, A_2\}, \{B_1, B_2\}, \underbrace{\{C_1, C_2, C_3, C_4\}}_{\text{Missing from ballot}}) \xrightarrow{\frac{3}{2}} (\{A_1, A_2\}, \{B_1, B_2\}, \{C_1\}, \underbrace{\{C_2, C_3, C_4\}}_{\text{Missing from ballot}})$$

The Borda proxy distance

The Borda proxy distance

In Ω_5 , Borda proxies are in 5-dimensional space.
The proxies of **ACB** is:

	A	B	C	D	E
ACB	4	2	3	0	0

KEY:

4 3 2 1 0

The Borda proxy distance

In Ω_5 , Borda proxies are in 5-dimensional space.
The proxies of **ACB** and **AE** are:

KEY:

4 3 2 1 0

	A	B	C	D	E
ACB	4	2	3	0	0
AE	4	0	0	0	3
<i>dif</i> =	<i>0</i>	<i>2</i>	<i>3</i>	<i>0</i>	<i>-3</i>

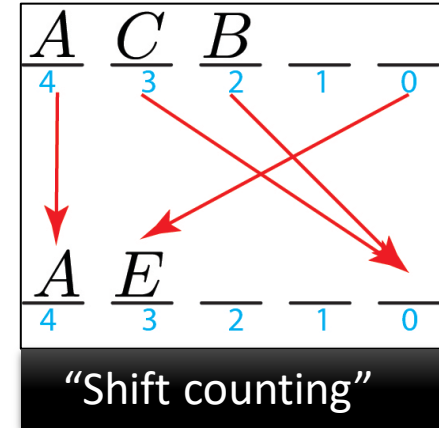
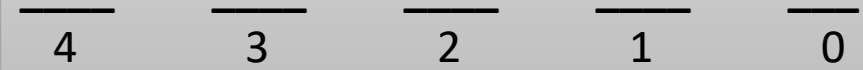
$d_B(\mathbf{ACB}, \mathbf{AE}) =$ the Manhattan distance between their proxies = 8.

The Borda proxy distance

In Ω_5 , Borda proxies are in 5-dimensional space.
The proxies of **ACB** and **AE** are:

	A	B	C	D	E
ACB	4	2	3	0	0
AE	4	0	0	0	3
<i>dif</i> =	0	2	3	0	-3

KEY:



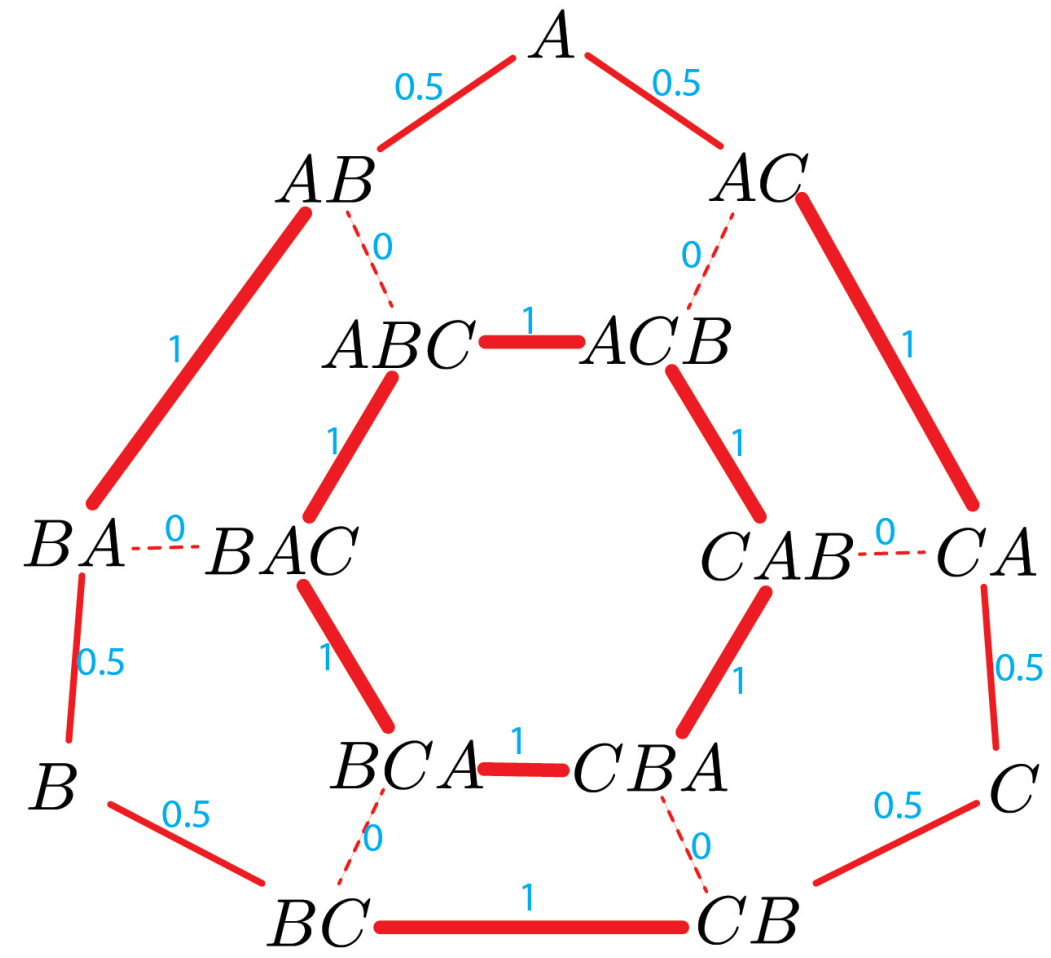
$d_B(\mathbf{ACB}, \mathbf{AE}) =$ the Manhattan distance between their proxies = 8.

Borda vs. head-to-head distance

- $1 < \frac{d_B}{d_H} \leq 2$.

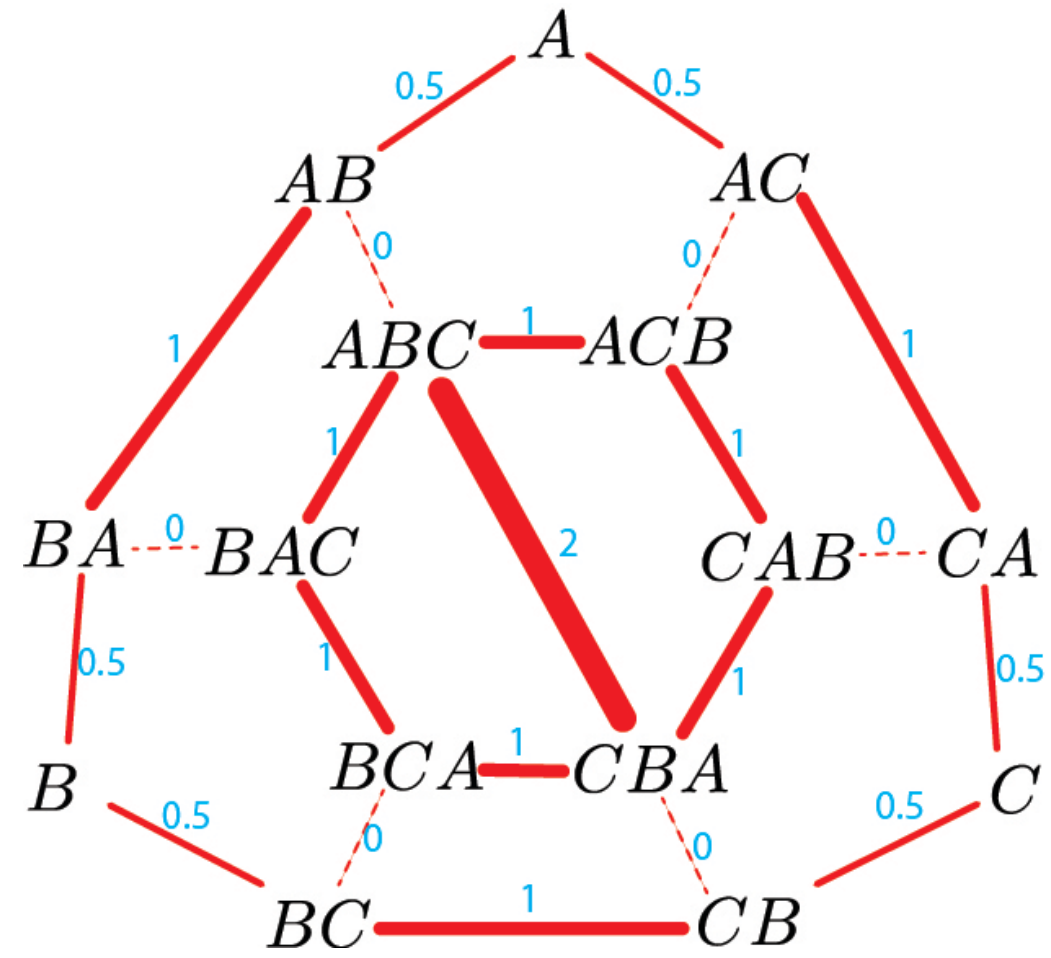
Borda vs. head-to-head distance

- $1 < \frac{d_B}{d_H} \leq 2$.
- $d_B = 2 d_H$ for adjacent pairs.



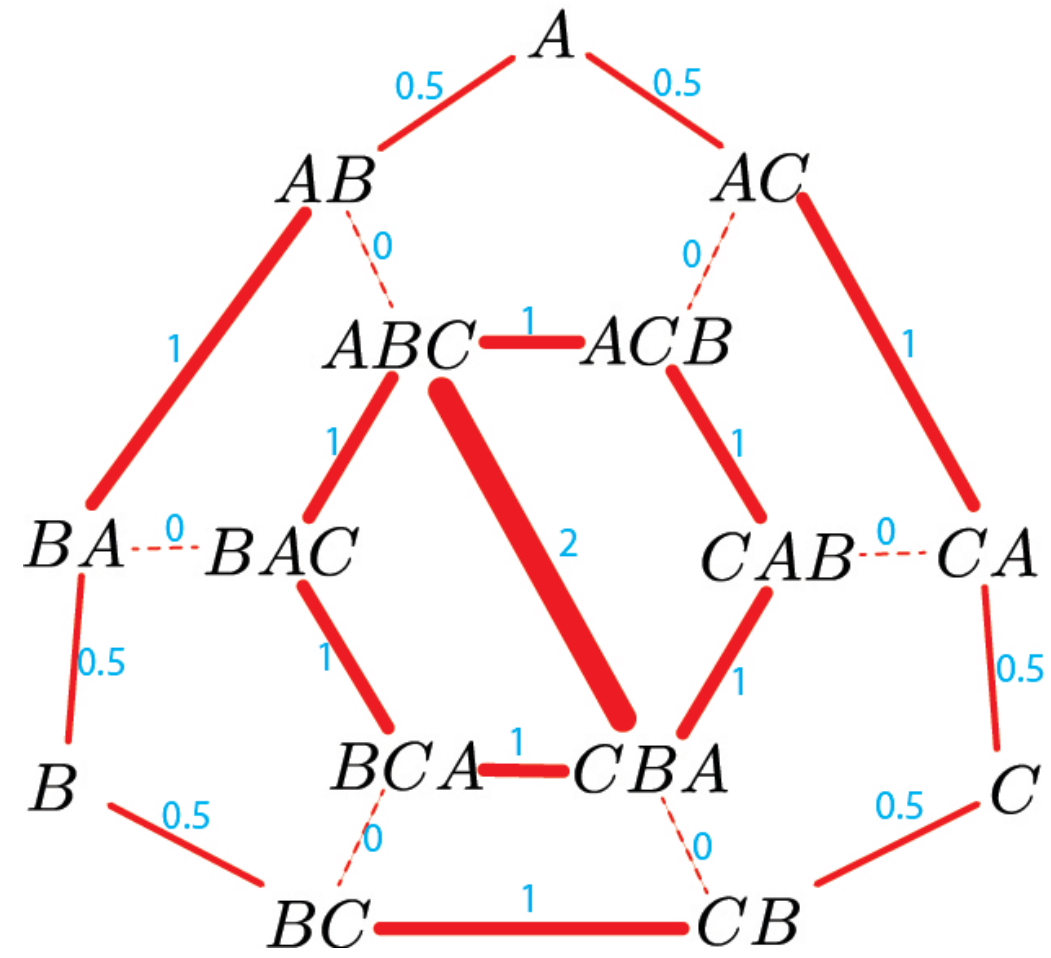
Borda vs. head-to-head distance

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- After adding an edge for each non-adjacent swap, d_B equals twice the graph distance.



Borda vs. head-to-head distance

- $1 < \frac{d_B}{d_H} \leq 2$.
- $d_B = 2 d_H$ for adjacent pairs.
- After adding an edge for each non-adjacent swap, d_B equals twice the graph distance.
- d_B penalizes strong disagreements a bit less than $2 d_H$.



Borda vs. head-to-head distance

$$2 d_H = 2 \cdot (\textit{strong}) + 1 \cdot (\textit{weak})$$

$$d_B = \alpha \cdot (\textit{strong}) + 1 \cdot (\textit{weak})$$

For $\alpha \in [1,2]$ that depends on the pair of ballots.

PROXY CLUSTERING: Associate each ballot to a proxy point of Euclidean space, and perform a standard clustering algorithm on the proxies.

1342 votes for (1, 6).

759 votes for (6, 1).

578 votes for (3, 5).

494 votes for (4).

403 votes for (3, 5, 7).

285 votes for (1, 6, 2).

254 votes for (1, 6, 4).

219 votes for (5, 3).

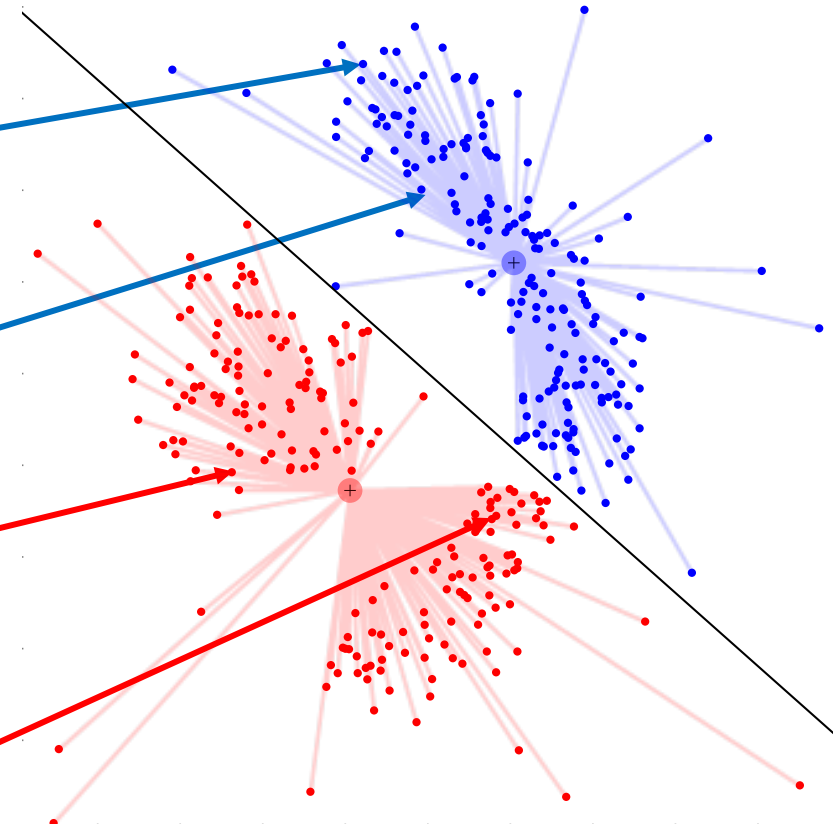
173 votes for (4, 2).

152 votes for (6, 1, 4).

144 votes for (5, 3, 7).

136 votes for (1, 6, 4, 2).

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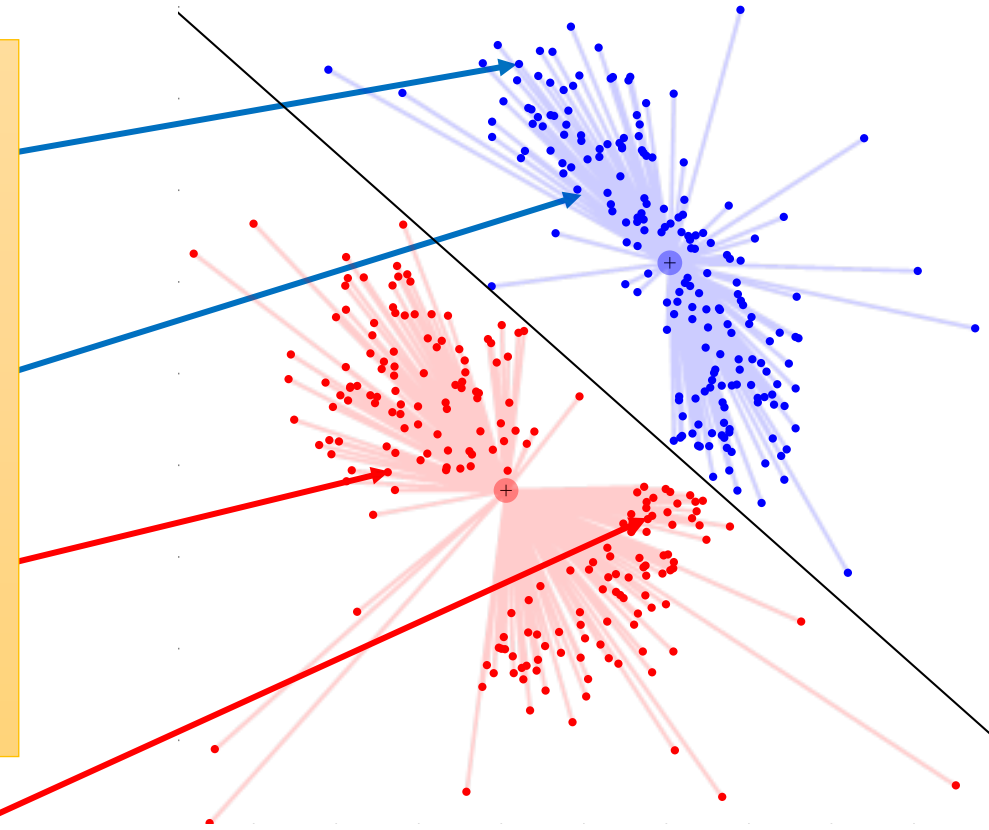
136 votes for (1, 6, 4, 2).

136 votes for (3, 5, 4)....

Borda or head-to-head proxies?

k-means or k-medoids?

All choices yield about the same clusters (~ 4%)



Only slight differenced between the methods
(averaged over elections from 17 wards of Edinburgh)

Proxy cluster methods

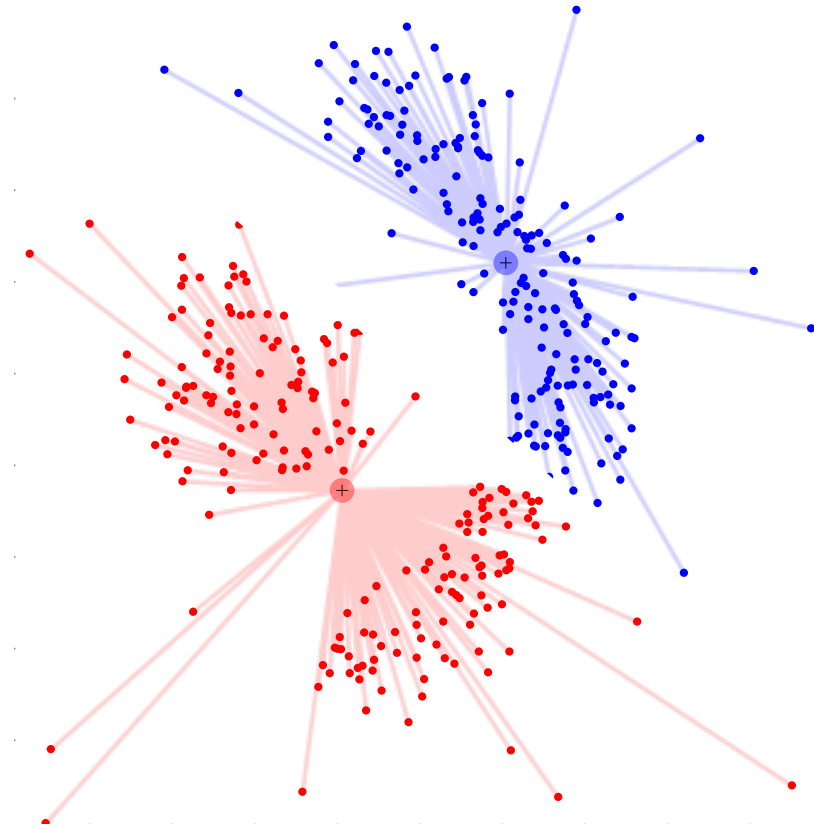
	MeanB	MeanH	MedoB	MedoH	Slate	Random
MeanB	0	0.014	0.052	0.039	0.077	0.431
MeanH	-	0	0.050	0.036	0.081	0.431
MedoB	-	-	0	0.032	0.076	0.429
MedoH	-	-	-	0	0.077	0.428
Slate	-	-	-	-	0	0.429
Random	-	-	-	-	-	0.459

k-means

- Center = centroid (center of mass)
- Minimizes summed squared L^2 distances of data points to their centers.

k-medoids

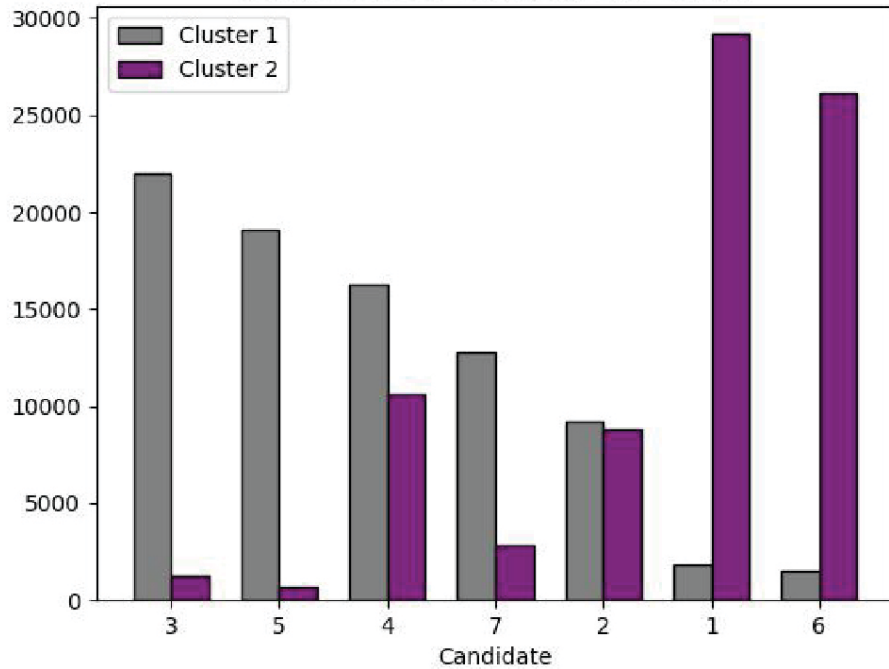
- Centers are data points
- Minimizes summed distance of data points to their center with respect to arbitrary metric (we use L^1).



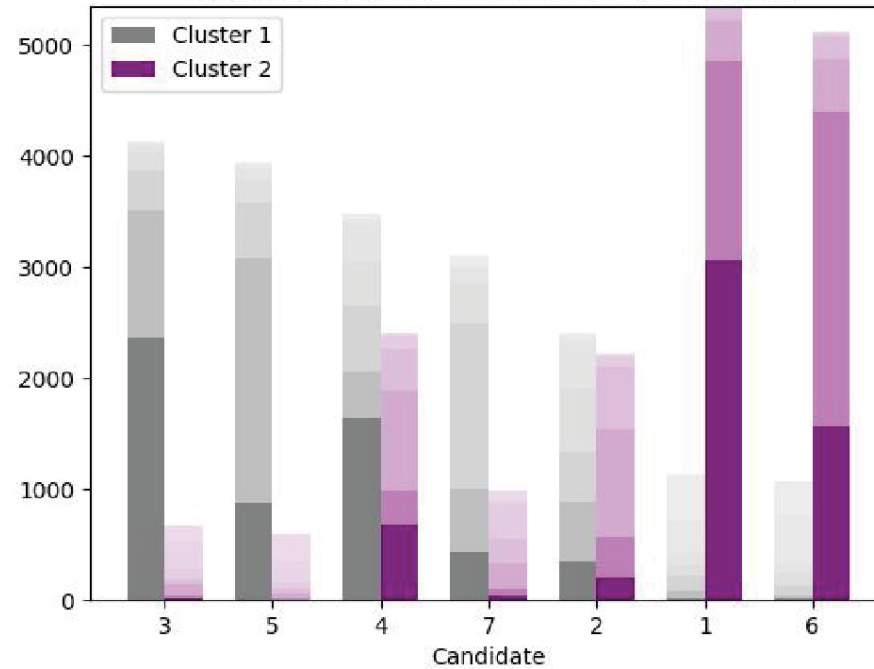
2-medoid clusters with head-to-head proxies.

Medoids: (3,5,7) and (1,6)

Borda Scores of Candidates by Cluster



Candidate Mentions Stacked by Ballot Position



SLATE CLUSTERING: Find the partition of the candidates into two slates A,B such that the ballots are most starkly divided into “A>B types” and “B>A types”. Partition the ballots accordingly.

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SLATE A:

3 = Neil Gardiner (SNP)

5 = Ernesta Noreikiene (SNP)

7 = Evelyn Weston (Grn)

SLATE B:

1 = Graeme Bruce (C)

2 = Emma Farthing (LD)

4 = Ricky Henderson (Lab)

6 = Susan Webber (C)

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METHOD: Exhaustively try all partitions to find the one with the best score.

SCORE = the sum of the distances of the ballots to “A>B” or “B>A” (whichever is closest)

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	A_1A_2	B_1B_2	B_1B_3	B_2B_3	A_1B_1	A_1B_2	A_1B_3	A_2B_1	A_2B_2	A_2B_3
$A_1B_2A_2$.5	-.5	0	.5	.5	.5	.5	.5	-.5	.5
$\{A_1, A_2\} > \{B_1, B_2, B_3\}$	0	0	0	0	.5	.5	.5	.5	.5	.5
$dif =$.5	-.5	0	.5	0	0	0	0	1	0

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	A_1A_2	B_1B_2	B_1B_3	B_2B_3	A_1B_1	A_1B_2	A_1B_3	A_2B_1	A_2B_2	A_2B_3
$A_1B_2A_2$.5	-.5	0	.5	.5	.5	.5	.5	-.5	.5
$\{A_1, A_2\} > \{B_1, B_2, B_3\}$	0	0	0	0	.5	.5	.5	.5	.5	.5
$dif =$.5	-.5	0	.5	0	0	0	0	1	0

not as relevant

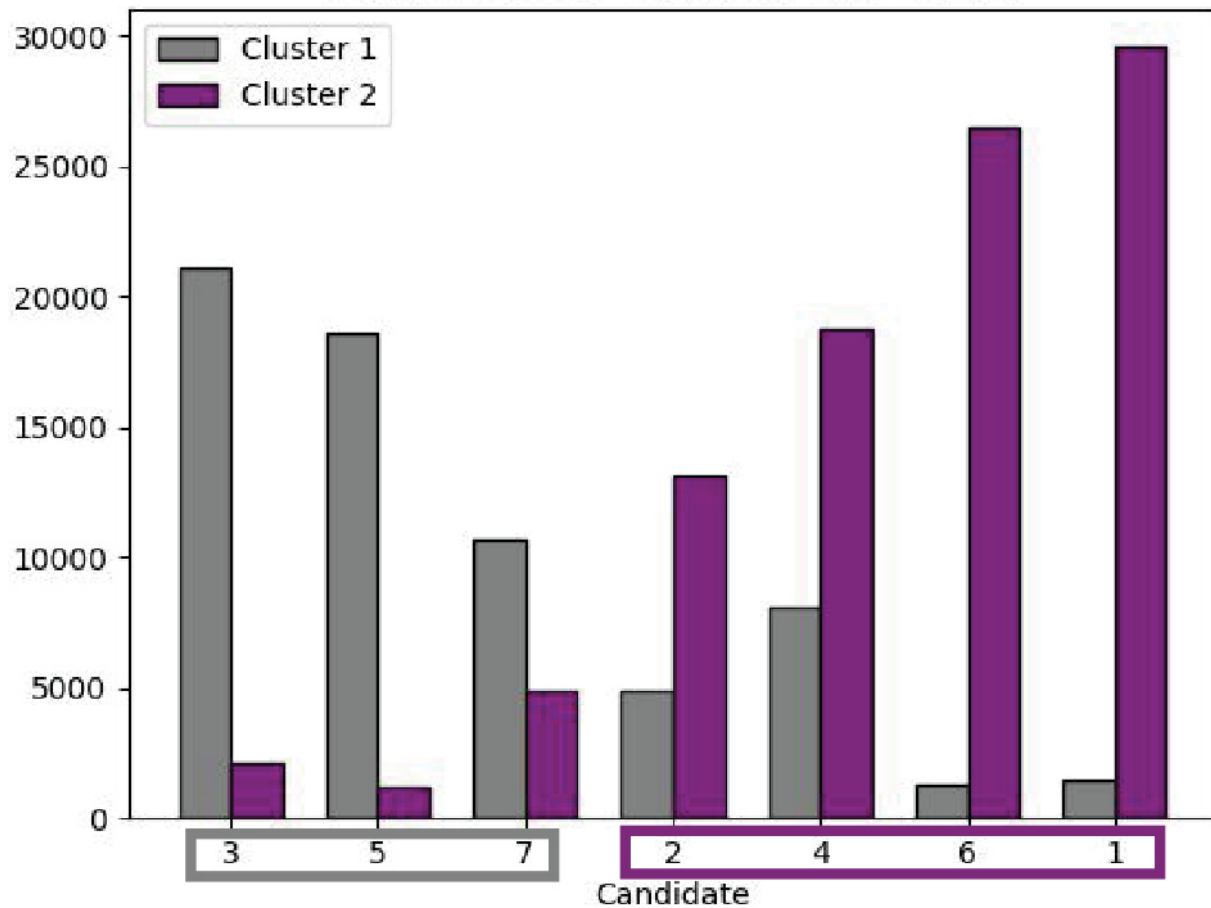
or just use this part

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Slate clusters

Borda Scores of Candidates by Cluster



Candidate Mentions Stacked by Ballot Position

